## F700

## INSTALLATION GUIDELINE FR－F720－00046 to 04750－NA FR－F740－00023 to 12120－NA

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## This section is specifically about safety matters

Do not attempt to install, operate, maintain or inspect the inverter until you have read through this Installation Guideline and appended documents carefully and can use the equipment correctly. Do not use the inverter until you have a full knowledge of the equipment, safety information and instructions. In this Installation Guideline, the safety instruction levels are classified into "WARNING" and "CAUTION".


Incorrect handling may cause hazardous conditions resulting in death or severe injury.


Incorrect handling may cause hazardous conditions, resulting in medium or slight injury, or may cause only material damage.

The $\triangle$ CAUTION level may even lead to a serious consequence according to conditions. Both instruction levels must be followed because these are important to personal safety.

## 1. Electric Shock Prevention

## WARNING

- While power is on or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.
- Do not run the inverter with the front cover removed. Otherwise, you may access the exposed high-voltage terminals or the charging part of the circuitry and get an electric shock.
- Even if power is off, do not remove the front cover except for wiring or periodic inspection. You may access the charged inverter circuits and get an electric shock. Before wiring, inspection or switching EMC filter ON/OFF connector power must be switched OFF. To confirm that, LED indication of the operation panel must be checked. (It must be OFF.) Any person who is involved in wiring, inspection or switching EMC filter ON/OFF connector shall wait for at least 10 minutes after the power supply has been switched OFF and check that there are no residual voltage using a tester or the like The capacitor is charged with high voltage for some time after power OFF, and it is dangerous.
This inverter must be grounded. Grounding must conform to the requirements of national and local safety regulations and electrical code (NEC section 250, IEC 536 class 1 and other applicable standards)
A neutral-point grounded power supply for 400 V class inverter in compliance with EN standard must be used.
- Any person who is involved in wiring or inspection of this equipment shall be fully competent to do the work.
- The inverter must be installed before wiring. Otherwise you may get an electric shock or be injured.
- Setting dial and key operations must be performed with dry hands to prevent an electric shock. Otherwise you may get an electric shock
- Do not subject the cables to scratches, excessive stress, heavy loads or pinching. Otherwise you may get an electric shock.
Do not replace the cooling fan while power is ON. It is dangerous to replace the cooling fan while power is ON.
- Do not touch the printed circuit board or handle the cables with wet hands Otherwise you may get an electric shock.
- When measuring the main circuit capacitor capacity (Pr. 259 Main circuit capacitor life measuring $=" 1 "$ ), the DC voltage is applied to the motor for 1 s at powering OFF. Never touch the motor terminal, etc. right after powering OFF to prevent an electric shock.


## 2. Fire Prevention $\triangle$ CAUTION

- Inverter must be installed on a nonflammable wall without holes (so that nobody touches the inverter heatsink on the rear side, etc.). Mounting it to or near flammable material can cause a fire.
- If the inverter has become faulty, the inverter power must be switched OFF. A continuous flow of large current could cause a fire.
- Do not connect a resistor directly to the DC terminals P/+ and N/-. Doing so could cause a fire.


## 3. Injury Prevention CAUTION

- The voltage applied to each terminal must be the ones specified in the Instruction Manual. Otherwise burst, damage, etc. may occur
- The cables must be connected to the correct terminals. Otherwise burst, damage, etc. may occur.
- Polarity must be correct. Otherwise burst, damage, etc. may occur.
- While power is ON or for some time after power-OFF, do not touch the inverter since the inverter will be extremely hot. Doing so can cause burns.


## 4. Additional Instructions

Also the following points must be noted to prevent an accidental failure, injury, electric shock, etc.

## (1) Transportation and installation <br> $\triangle$ CAUTION

- The product must be transported in correct method that corresponds to the weight. Failure to do so may lead to injuries.
- Do not stack the boxes containing inverters higher than the number recommended.
- The product must be installed to the position where withstands the weight of the product according to the information in the Instruction Manual.
- Do not install or operate the inverter if it is damaged or has parts missing. This can result in breakdowns.
- When carrying the inverter, do not hold it by the front cover or setting dial; it may fall off or fail.
- Do not stand or rest heavy objects on the product.
- The inverter mounting orientation must be correct.
- Foreign conductive bodies must be prevented to enter the inverter. That includes screws and metal fragments or other flammable substance such as oil.
- As the inverter is a precision instrument, do not drop or subject it to impact.
The inverter must be used under the following environment: Otherwise the inverter may be damaged.

|  |  |  | LD | $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ to $\left.122^{\circ} \mathrm{F}\right)$ (non-freezing) |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | SLD <br> (initial setting) | $-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ to $\left.104^{\circ} \mathrm{F}\right)($ non-freezing) |
|  |  | Ambient humidity |  | 90\% RH or less (non-condensing) |
|  |  | Storage temperature |  | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C} * 1\left(-0^{\circ} \mathrm{F}\right.$ to $\left.149^{\circ} \mathrm{F}\right)$ |
|  |  | Atmosphere |  | Indoors (free from corrosive gas, flammable gas, oil mist, dust and dirt) |
|  |  | Altitude, vibration |  | Maximum 1000m (3280.80feet) above sea level for standard operation. After that derate by $3 \%$ for every extra 500 m ( 1640.40 feet) up to 2500 m (8202feet) $(92 \%) 5.9 \mathrm{~m} / \mathrm{s}^{2}$ or less *2 at 10 to 55 Hz (directions of $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ axes) |

*1 Temperature applicable for a short time, e.g. in transit.
*2 $2.9 \mathrm{~m} / \mathrm{s}^{2}$ or less for the FR-F740-04320 or more.

## (2) Wiring $\triangle$ CAUTION

- Do not install a power factor correction capacitor or surge suppressor on the inverter output side. These devices on the inverter output side may be overheated or burn out.
- The connection orientation of the output cables $\mathrm{U}, \mathrm{V}, \mathrm{W}$ to the motor will affect the direction of rotation of the motor.


## (3) Test operation and adjustment

## ©CAUTION

- Before starting operation, each parameter must be confirmed and adjusted. A failure to do so may cause some machines to make unexpected motions.


## (4) Operation 1 I WRRNING

- Any person must stay away from the equipment when the retry function is set as it will restart suddenly after trip.
- Since pressing ( $\left.\frac{\text { STOP }}{\text { RRSET }}\right)$ key may not stop output depending on the function setting status, separate circuit and switch that make an emergency stop (power OFF, mechanical brake operation for emergency stop, etc.) must be provided.
- OFF status of the start signal must be confirmed before resetting the inverter fault. Resetting inverter alarm with the start signal ON restarts the motor suddenly
- The inverter must be used for three-phase induction motors.

Connection of any other electrical equipment to the inverter output may damage the equipment.

- Do not modify the equipment.
- Do not perform parts removal which is not instructed in this manual. Doing so may lead to fault or damage of the inverter.


## ACAUTION

- The electronic thermal relay function does not guarantee protection of the motor from overheating. It is recommended to install both an external thermal and PTC thermistor for overheat protection.
- Do not use a magnetic contactor on the inverter input for frequent starting/ stopping of the inverter.
- The effect of electromagnetic interference must be reduced by using a noise filter or by other means. Otherwise nearby electronic equipment may be affected.
- Appropriate measures must be taken to suppress harmonics. Otherwise power supply harmonics from the inverter may heat/damage the power factor correction capacitor and generator.
- When driving a 400 V class motor by the inverter, the motor must be an insulation-enhanced motor or measures must be taken to suppress surge voltage. Surge voltage attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor.
- When parameter clear or all parameter clear is performed, the required parameters must be set again before starting operations because al parameters return to the initial value
- The inverter can be easily set for high-speed operation. Before changing its setting, the performances of the motor and machine must be fully examined.
- Stop status cannot be hold by the inverter's brake function. In addition to the inverter's brake function, a holding device must be installed to ensure safety.
- Before running an inverter which had been stored for a long period, inspection and test operation must be performed.
- For prevention of damage due to static electricity, nearby metal must be touched before touching this product to eliminate static electricity from your body.


## (5) Emergency stop 1 CAUTION

- A safety backup such as an emergency brake must be provided to prevent hazardous condition to the machine and equipment in case of inverter failure.
- When the breaker on the inverter input side trips, the wiring must be checked for fault (short circuit), and internal parts of the inverter for a damage, etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.
- When any protective function is activated, appropriate corrective action must be taken, and the inverter must be reset before resuming operation.


## (6) Maintenance, inspection and parts replacement <br> $\triangle$ CAUTION

- Do not carry out a megger (insulation resistance) test on the control circuit of the inverter. It will cause a failure.


## (7) Disposing of the inverter <br> - The inverter must be treated as industrial waste.

## General instructions

Many of the diagrams and drawings in Instruction Manuals show the inverter without a cover or partially open for explanation. Never operate the inverter in this manner. The cover must be always reinstalled and the instruction in Instruction Manuals must be followed when operating the inverter

## 1 INSTALLATION OF THE INVERTER AND INSTRUCTIONS

## - Inverter Model




## - Installation of the inverter

Note - Some inverter models may be installed outside an enclosure. See Appendix 2 for details.
Installation on the enclosure

FR-F720-01250 or less
FR-F740-00620 or less


FR-F720-01540 or more FR-F740-00770 or more


CAUTION
When encasing multiple inverters, install them in parallel as a cooling measure.

*1 1 cm or more for FR-F720-00167 (FR-F740-00083) or less 10 cm or more for FR-F720-03160 (FR-F740-01800) or more
$2 \mathbf{2 0} \mathrm{~cm}$ or more for FR-F720-03160 (FR-F740-01800) or more

Fix six positions for the FR-F74004320 to 08660 and fix eight positions for the FR-F740-09620 to 12120.

## - General Precaution

The bus capacitor discharge time is 10 minutes. Before starting wiring or inspection, switch power off, wait for more than 10 minutes, and check for residual voltage between terminal P/+ and N/- with a meter etc., to avoid a hazard of electrical shock.

- Environment

Before installation, check that the environment meets following specifications.

| Surrounding Air Temperature | LD: $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ to $\left.122^{\circ} \mathrm{F}\right)$ Maximum (nonfreezing) <br> SLD (initial setting): $-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ to $\left.104^{\circ} \mathrm{F}\right)$ Maximum (non-freezing) | 5 cm <br> (1.97inches) <br> Measuremen position |  |
| :---: | :---: | :---: | :---: |
| Ambient humidity | 90\%RH or less (non-condensing) |  |  |
| Storage temperature | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right.$ to $\left.149^{\circ} \mathrm{F}\right)$ |  |  |
| Ambience | Indoors (No corrosive and flammable gases, oil mist, dust and dirt.) |  |  |
| Altitude, vibration | Below $1000 \mathrm{~m}, 5.9 \mathrm{~m} / \mathrm{s}^{2}$ or less at 10 to 55 Hz (directions of $X, Y, Z$ axes) $\left(2.9 \mathrm{~m} / \mathrm{s}^{2}\right.$ or less for the FR-F740-04320 or more) |  |  |

## CAUTION

- Install the inverter on a non-combustible wall surface such as metal or concrete.
- Mount the inverter on a strong surface securely and vertically with bolts.
- Provide sufficient clearance distances away from other devices.
- WARNING: HEAT SINK SURFACE MAY BE HOT. TO REDUCE RISK OF BURN - DO NOT TOUCH.


## 2 OUTLINE DRAWING

FR-F720-00046 to 04750-NA
FR-F740-00023 to 03610-NA


RR-F740-04320 to 08660-NA


FR-F740-09620 to 12120-NA


(Unit:mm(inches))
-200V class

| Inverter Model | W | W1 | H | H1 | D |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F720-00046-NA | 110 (4.33) | 95 (3.74) | 260 (10.24) | 245 (9.65) | 110 (4.33) |
| FR-F720-00077-NA |  |  |  |  | 125 (4.92) |
| FR-F720-00105-NA | 150 (5.91) | 125 (4.92) |  |  | 140 (5.51) |
| FR-F720-00167-NA |  |  |  |  |  |
| FR-F720-00250-NA |  |  |  |  |  |
| FR-F720-00340-NA | 220 (8.66) | 195 (7.68) |  |  | 170 (6.69) |
| FR-F720-00490-NA |  |  |  |  |  |
| FR-F720-00630-NA |  |  | 300 (11.81) | 285 (11.22) | 190 (7.48) |
| FR-F720-00770-NA | 250 (9.84) | 230 (9.06) | 400 (15.75) | 380 (14.96) |  |
| FR-F720-00930-NA |  |  |  |  |  |
| FR-F720-01250-NA |  |  |  |  |  |
| FR-F720-01540-NA | 325 (12.8) | 270 (10.63) | 550 (21.65) | 530 (20.87) | 195 (7.68) |
| FR-F720-01870-NA | 435 (17.13) | 380 (14.96) |  | 525 (20.67) | 250 (9.84) |
| FR-F720-02330-NA |  |  |  |  |  |
| FR-F720-03160-NA | 465 (18.31) | 400 (15.75) | 740 (29.13) | 715 (28.15) | 360 (14.17) |
| FR-F720-03800-NA |  |  |  |  |  |
| FR-F720-04750-NA |  |  |  |  |  |

-400V class

| Inverter Model | W | W1 | H | H1 | D |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F740-00023-NA | 150 (5.91) | 125 (4.92) | 260 (10.24) | 245 (9.65) | 140 (5.51) |
| FR-F740-00038-NA |  |  |  |  |  |
| FR-F740-00052-NA |  |  |  |  |  |
| FR-F740-00083-NA |  |  |  |  |  |
| FR-F740-00126-NA |  |  |  |  |  |
| FR-F740-00170-NA | 220 (8.66) | 195 (7.68) |  |  | 170 (6.69) |
| FR-F740-00250-NA |  |  |  |  |  |
| FR-F740-00310-NA |  |  | 300 (11.81) | 285 (11.22) | 190 (7.48) |
| FR-F740-00380-NA |  |  |  |  |  |
| FR-F740-00470-NA | 250 (9.84) | 230 (9.06) | 400 (15.75) | 380 (14.96) | 190 (7.48) |
| FR-F740-00620-NA |  |  |  |  |  |
| FR-F740-00770-NA | 325 (12.8) | 270 (10.63) | 550 (21.65) | 530 (20.87) | 195 (7.68) |
| FR-F740-00930-NA | 435 (17.13) | 380 (14.96) | 550 (21.65) | 525 (20.67) | 250 (9.84) |
| FR-F740-01160-NA |  |  |  |  |  |
| FR-F740-01800-NA |  |  |  |  |  |
| FR-F740-02160-NA | 465 (18.31) | 400 (15.75) | 620 (24.41) | 595 (23.43) | 300 (11.81) |
| FR-F740-02600-NA |  |  |  |  |  |
| FR-F740-03250-NA |  |  | 740 (29.13) | 715 (28.15) | 360 (14.17) |
| FR-F740-03610-NA |  |  |  |  |  |
| FR-F740-04320-NA | 498 (19.6) | 200 (7.87) | 1010 (39.76) | 984 (38.77) | 380 (14.96) |
| FR-F740-04810-NA |  |  |  |  |  |
| FR-F740-05470-NA | 680 (26.77) | 300 (11.81) |  |  |  |
| FR-F740-06100-NA |  |  |  |  |  |
| FR-F740-06830-NA |  |  |  |  |  |
| FR-F740-07700-NA | 790 (31.1) | 315 (12.4) | 1330 (52.36) | 1300 (51.18) | 440 (17.32) |
| FR-F740-08660-NA | 790 (31.1) | 315 (12.4) |  |  |  |
| FR-F740-09620-NA | 995 (39.17) | 300 (11.81) | 1580 (62.2) | 1550 (61.02) |  |
| FR-F740-10940-NA |  |  |  |  |  |
| FR-F740-12120-NA |  |  |  |  |  |

## 3 WIRING



## CAUTION

- To prevent a malfunction due to noise, keep the signal cables more than 10 cm away from the power cables. Also separate the main circuit wire of the input side and the output side
- After wiring, wire offcuts must not be left in the inverter.

Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.
When drilling mounting holes in a control box etc., take care not to allow chips and other foreign matter to enter the inverter.
Set the voltage/current input switch correctly. Different setting may cause a fault, failure or malfunction.

### 3.1 Main circuit terminal

## (1) Terminal layout and wiring

200 V class

| FR-F720-00046, 00077-NA <br> As this is an inside cover fixing screw, do not remove it. | FR-F720-00105 to 00250-NA |
| :---: | :---: |
| FR-F720-00340, 00490-NA <br> * Screw size of terminal <br> Screw size (M5) R1/L11, S1/L21, PR and PX is M 4 . |  |
|  | FR-F720-01540 to 02330-NA |

FR-F720-03160 to 04750-NA

(for option)

## 400 V class

| FR-F740-00023 to 00126-NA |  |
| :---: | :---: |
| FR-F740-00310, 00380-NA | FR-F740-00470, 00620-NA |


| FR-F740-00770 to 01160-NA |  |
| :---: | :---: |
| FR-F740-03250 to 04810-NA | FR-F740-05470 to 12120-NA |

## - CAUTION

The power supply cables must be connected to R/L1, S/L2, T/L3. (Phase sequence needs not to be matched.) Never connect the power cable to the $\mathrm{U}, \mathrm{V}, \mathrm{W}$ of the inverter. Doing so will damage the inverter.

- Connect the motor to U, V, W. At this time, turning ON the forward rotation switch (signal) rotates the motor in the counterclockwise direction when viewed from the motor shaft.
When wiring the inverter main circuit conductor of the FR-F740-05470 or more, tighten a nut from the right side of the conductor. When wiring two wires, place wires on both sides of the conductor. (Refer to the drawing below.) For wiring, use bolts (nuts) provided with the inverter.



## (2) Cable size

Select the recommended cable size to ensure that a voltage drop will be $2 \%$ or less.
If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.
The following table indicates a selection example for the wiring length of 20 m ( 65.62 feet ).
200 V class (when input power supply is 220 V )

| Applicable Inverter Model | Terminal Screw Size *4 | Tightening Torque $\mathrm{N} \cdot \mathrm{m}$ | Crimping Terminal |  | Cable Sizes |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | HIV, etc. $\left(\mathrm{mm}^{2}\right){ }^{1}$ |  |  |  | AWG/MCM * 2 |  | PVC, etc. ( $\mathrm{mm}^{2}$ ) *3 |  |  |
|  |  |  | $\begin{aligned} & \text { R/L1, } \\ & \text { S/2, } \\ & \text { T/L3 } \end{aligned}$ | U, V, W | R/L1, <br> S/L2, <br> T/L3 | $\mathrm{U}, \mathrm{V}, \mathrm{W}$ | P/+, P1 | Ground cable | $\begin{aligned} & \mathrm{R} / \mathrm{L} 1, \\ & \mathrm{~S} / \mathrm{L} 2, \\ & \mathrm{~T} / \mathrm{L} 3 \\ & \hline \end{aligned}$ | U, V, W | $\begin{aligned} & \text { R/L1, } \\ & \text { S/L2, } \\ & \text { T/L3 } \end{aligned}$ | U, V, W | Ground cable |
| $\begin{aligned} & \text { FR-F720-00046 to } \\ & \text { 00105-NA } \end{aligned}$ | M4 | 1.5 | 2-4 | 2-4 | 2 | 2 | 2 | 2 | 14 | 14 | 2.5 | 2.5 | 2.5 |
| FR-F720-00167-NA | M4 | 1.5 | 5.5-4 | 5.5-4 | 3.5 | 3.5 | 3.5 | 3.5 | 12 | 12 | 4 | 4 | 4 |
| FR-F720-00250-NA | M4 | 1.5 | 5.5-4 | 5.5-4 | 5.5 | 5.5 | 5.5 | 5.5 | 10 | 10 | 6 | 6 | 6 |
| FR-F720-00340-NA | M5 | 2.5 | 14-5 | 8-5 | 14 | 8 | 14 | 5.5 | 6 | 8 | 16 | 10 | 16 |
| FR-F720-00490-NA | M5 | 2.5 | 14-5 | 14-5 | 14 | 14 | 14 | 14 | 6 | 6 | 16 | 16 | 16 |
| FR-F720-00630-NA | M5 | 2.5 | 22-5 | 22-5 | 22 | 22 | 22 | 14 | 4 | 6 (*5) | 25 | 25 | 16 |
| FR-F720-00770-NA | M6 | 4.4 | 38-6 | 38-6 | 38 | 38 | 38 | 22 | 2 | 2 | 50 | 50 | 25 |
| FR-F720-00930-NA | M8(M6) | 7.8 | 38-8 | 38-8 | 38 | 38 | 38 | 22 | 2 | 2 | 50 | 50 | 25 |
| FR-F720-01250-NA | M8(M6) | 7.8 | 60-8 | 60-8 | 60 | 60 | 60 | 22 | 1/0 | 1/0 | 50 | 50 | 25 |
| FR-F720-01540-NA | M8(M6) | 7.8 | 80-8 | 80-8 | 80 | 80 | 80 | 22 | 3/0 | 3/0 | 70 | 70 | 35 |
| FR-F720-01870-NA | M10(M8) | 14.7 | 100-10 | 100-10 | 100 | 100 | 100 | 38 | 4/0 | 4/0 | 95 | 95 | 50 |
| FR-F720-02330-NA | M10(M8) | 14.7 | 100-10 | 100-10 | 100 | 100 | 100 | 38 | 4/0 | 4/0 | 95 | 95 | 50 |
| FR-F720-03160-NA | M12(M10) | 24.5 | 150-12 | 150-12 | 125 | 125 | 150 | 38 | 250 | 250 | - | - | - |
| FR-F720-03800-NA | M12(M10) | 24.5 | 150-12 | 150-12 | 150 | 150 | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | - | - | - |
| FR-F720-04750-NA | M12(M10) | 24.5 | 100-12 | 100-12 | 2×100 | $2 \times 100$ | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | - | - | - |

*1 The recommended cable size is that of the cable (e.g. HIV cable ( 600 V class 2 vinyl-insulated cable)) with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}\left(167^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$ or less and the wiring distance is $20 \mathrm{~m}(65.62 \mathrm{feet})$ or less.
*2 The recommended cable size is that of the cable ( THHW cable) with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}$ ( $167^{\circ} \mathrm{F}$ ). Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and the wiring distance is 20 m ( 65.62 feet ) or less. (Selection example for use mainly in the United States.)
*3 For the FR-F720-00930 or less, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of $70^{\circ} \mathrm{C}\left(158^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and the wiring distance is $20 \mathrm{~m}(65.62 \mathrm{feet})$ or less.
For the FR-F720-01250 or more, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and wiring is performed in an enclosure. (Selection example for use mainly in Europe.)
*4 The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for grounding. A screw for earthing (grounding) of the FR-F720-00930 or more is indicated in ( ).
*5 When connecting the option unit to P/+, P1, N/-, use THHN cables for the option and terminals R/L1, S/L2, T/L3, U, V, W.

400 V class (when input power supply is 440 V based on the rated current for $110 \%$ overload for 1 minute)

| Applicable Inverter Model | TerminalScrew Size*4 | Tightening Torque N•m | Crimping (Compression) Terminal |  | Cable Sizes |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | HIV, etc. (mm2) *1 |  |  |  | AWG/MCM *2 |  | PVC, etc. (mm2) *3 |  |  |
|  |  |  | R/L1, S/L2, T/L3 | U, V, W | R/L1, S/L2, T/L3 | U, V, W | P/+, P1 | Ground cable | R/L1, S/L2, T/L3 | U, V, W | R/L1, S/L2, T/L3 | U, V, W | Ground cable |
| $\begin{aligned} & \text { FR-F740-00023 to } \\ & \text { O0083-NA } \end{aligned}$ | M4 | 1.5 | 2-4 | 2-4 | 2 | 2 | 2 | 2 | 14 | 14 | 2.5 | 2.5 | 2.5 |
| FR-F740-00126-NA | M4 | 1.5 | 2-4 | 2-4 | 2 | 2 | 3.5 | 3.5 | 12 | 14 | 2.5 | 2.5 | 4 |
| FR-F740-00170-NA | M4 | 1.5 | 5.5-4 | 5.5-4 | 3.5 | 3.5 | 3.5 | 3.5 | 12 | 12 | 4 | 4 | 4 |
| FR-F740-00250-NA | M4 | 1.5 | 5.5-4 | 5.5-4 | 5.5 | 5.5 | 5.5 | 8 | 10 | 10 | 6 | 6 | 10 |
| FR-F740-00310-NA | M5 | 2.5 | 8-5 | 8-5 | 8 | 8 | 8 | 8 | 8 | 8 | 10 | 10 | 10 |
| FR-F740-00380-NA | M5 | 2.5 | 14-5 | 8-5 | 14 | 8 | 14 | 14 | 6 | 8 | 16 | 10 | 16 |
| FR-F740-00470-NA | M6 | 4.4 | 14-6 | 14-6 | 14 | 14 | 22 | 14 | 6 | 6 | 16 | 16 | 16 |
| FR-F740-00620-NA | M6 | 4.4 | 22-6 | 22-6 | 22 | 22 | 22 | 14 | 4 | 4 | 25 | 25 | 16 |
| FR-F740-00770-NA | M6 | 4.4 | 22-6 | 22-6 | 22 | 22 | 22 | 14 | 4 | 4 | 25 | 25 | 16 |
| FR-F740-00930-NA | M8 | 7.8 | 38-8 | 38-8 | 38 | 38 | 38 | 22 | 1 | 2 | 50 | 50 | 25 |
| FR-F740-01160-NA | M8 | 7.8 | 60-8 | 60-8 | 60 | 60 | 60 | 22 | 1/0 | 1/0 | 50 | 50 | 25 |
| FR-F740-01800-NA | M8 | 7.8 | 60-8 | 60-8 | 60 | 60 | 60 | 38 | 1/0 | 1/0 | 50 | 50 | 25 |
| FR-F740-02160-NA | M10 | 14.7 | 100-10 | 100-10 | 80 | 80 | 80 | 38 | 3/0 | 3/0 | 70 | 70 | 35 |
| FR-F740-02600-NA | M10 | 14.7 | 100-10 | 100-10 | 100 | 100 | 100 | 38 | 4/0 | 4/0 | 95 | 95 | 50 |
| FR-F740-03250-NA | M10 | 14.7 | 150-10 | 150-10 | 125 | 125 | 100 | 38 | 250 | 250 | 120 | 120 | 70 |
| FR-F740-03610-NA | M10 | 14.7 | 150-10 | 150-10 | 150 | 150 | 150 | 38 | 300 | 300 | 150 | 150 | 95 |
| FR-F740-04320-NA | M12(M10) | 24.5 | 100-12 | 100-12 | $2 \times 100$ | $2 \times 100$ | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | $2 \times 95$ | $2 \times 95$ | 95 |
| FR-F740-04810-NA | M12(M10) | 24.5 | 100-12 | 100-12 | $2 \times 100$ | $2 \times 100$ | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | $2 \times 95$ | $2 \times 95$ | 95 |
| FR-F740-05470-NA | M12(M10) | 46 | 150-12 | 150-12 | $2 \times 125$ | $2 \times 125$ | $2 \times 125$ | 38 | $2 \times 250$ | $2 \times 250$ | $2 \times 120$ | $2 \times 120$ | 120 |
| FR-F740-06100-NA | M12(M10) | 46 | 150-12 | 150-12 | $2 \times 150$ | $2 \times 150$ | $2 \times 125$ | 60 | $2 \times 300$ | $2 \times 300$ | $2 \times 150$ | $2 \times 150$ | 150 |
| FR-F740-06830-NA | M12(M10) | 46 | 200-12 | 200-12 | $2 \times 200$ | $2 \times 200$ | $2 \times 150$ | 60 | $2 \times 350$ | $2 \times 350$ | $2 \times 185$ | $2 \times 185$ | $2 \times 95$ |
| FR-F740-07700-NA | M12(M10) | 46 | C2-200 | C2-200 | $2 \times 200$ | $2 \times 200$ | $2 \times 200$ | 60 | $2 \times 400$ | $2 \times 400$ | $2 \times 185$ | $2 \times 185$ | 2×95 |
| FR-F740-08660-NA | M12(M10) | 46 | C2-250 | C2-250 | $2 \times 250$ | $2 \times 250$ | $2 \times 200$ | 60 | $2 \times 500$ | $2 \times 500$ | $2 \times 240$ | $2 \times 240$ | $2 \times 120$ |
| FR-F740-09620-NA | M12(M10) | 46 | C2-250 | C2-250 | $2 \times 250$ | $2 \times 250$ | $2 \times 250$ | 100 | $2 \times 500$ | $2 \times 500$ | $2 \times 240$ | $2 \times 240$ | $2 \times 120$ |
| FR-F740-10940-NA | M12(M10) | 46 | C2-200 | C2-200 | $3 \times 200$ | $3 \times 200$ | $3 \times 200$ | 100 | $3 \times 350$ | $3 \times 350$ | $3 \times 185$ | $3 \times 185$ | $2 \times 150$ |
| FR-F740-12120-NA | M12(M10) | 46 | C2-200 | C2-200 | $3 \times 200$ | $3 \times 200$ | $3 \times 200$ | 100 | $3 \times 400$ | $3 \times 400$ | $3 \times 185$ | $3 \times 185$ | $2 \times 150$ |

*1 For the FR-F740-01160 or less, the recommended cable size is that of the cable (e.g. HIV cable ( 600 V class 2 vinyl-insulated cable)) with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}\left(167^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$ or less and the wiring distance is 20 m ( 65.62 feet ) or less.
For the FR-F740-01800 or more, the recommended cable size is that of the cable (e.g. LMFC (heat resistant flexible cross-linked polyethylene insulated cable)) with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$ or less and wiring is performed in an enclosure.
*2 For the FR-F740-00930 or less, the recommended cable size is that of the cable (THHW cable) with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}\left(167^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and the wiring distance is 20 m ( 65.62 feet ) or less.
For the FR-F740-01160 or more, the recommended cable size is that of the cable (THHN cable) with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and wiring is performed in an enclosure. (Selection example for use mainly in the United States.)
*3 For the FR-F740-00930 or less, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of $70^{\circ} \mathrm{C}\left(158^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and the wiring distance is 20 m ( 65.62 feet) or less.
For the FR-F740-01160 or more, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ or less and wiring is performed in an enclosure.
(Selection example for use mainly in the Europe.)
*4 The terminal screw size indicates the terminal size for $R / L 1, S / L 2, T / L 3, U, V, W$, and a screw for grounding. A screw for earthing (grounding) of the FR-F740-04320 or more is indicated in ( ).
The line voltage drop can be calculated by the following formula:
Line voltage drop $[\mathrm{V}]=\frac{\sqrt{3} \times \text { wire resistance }[\mathrm{m} \Omega / \mathrm{m}] \times \text { wiring distance }[\mathrm{m}] \times \text { current }[\mathrm{A}]}{1000}$
Use a larger diameter cable when the wiring distance is long or when it is desired to decrease the voltage drop (torque reduction) in the low speed range.

## CAUTION

Tighten the terminal screw to the specified torque.
A screw that has been tighten too loosely can cause a short circuit or malfunction.
A screw that has been tighten too tightly can cause a short circuit or malfunction due to the unit breakage.
Use crimping terminals with insulation sleeve to wire the power supply and motor.

## (3) Total wiring length

The overall wiring length for connection of a single motor or multiple motors should be within the value in the table below.

| Pr. 72 PWM frequency selection setting (carrier frequency) | $\begin{aligned} & \text { FR-F720-00046 } \\ & \text { FR-F740-00023 } \end{aligned}$ | $\begin{aligned} & \hline \text { FR-F720-00077 } \\ & \text { FR-F740-00038 } \end{aligned}$ | FR-F720-00105 or more FR-F740-00052 or more |
| :---: | :---: | :---: | :---: |
| $2(2 \mathrm{kHz})$ or less | $\begin{gathered} 300 \mathrm{~m} \\ (984.25 \mathrm{feet}) \end{gathered}$ | $\begin{gathered} 500 \mathrm{~m} \\ (1640.42 \mathrm{feet}) \end{gathered}$ | 500m (1640.42feet) |
| 3 to 15 (3kHz to 14.5 kHz$)$ | $\begin{gathered} \hline 200 \mathrm{~m} \\ (656.19 \mathrm{feet}) \\ \hline \end{gathered}$ | $\begin{gathered} 300 \mathrm{~m} \\ (984.25 \text { feet }) \end{gathered}$ | 500m (1640.42feet) |

When driving a 400 V class motor by the inverter, surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor. Take the following measures in this case.
Take the following measures (1) or (2) in this case.
(1) Use a "400V class inverter-driven insulation-enhanced motor" and set frequency in Pr. 72 PWM frequency selection according to wiring length.

|  | Wiring Length |  |  |
| :---: | :---: | :---: | :---: |
|  | 50 m (164.04feet) or <br> less | $50 \mathrm{~m}(164.04 \mathrm{feet)}$ to <br> $100 \mathrm{~m}(328.08 \mathrm{feet})$ | exceeding 100m <br> (328.08feet) |
| Pr. 72 PWM frequency selection setting <br> (carrier frequency) | 14.5 kHz or less | 9 kHz or less | 4 kHz or less |

(2) Connect the surge voltage suppression filter (FR-ASF-H) to the FR-F720-02330 (FR-F740-01160) or less and the sine wave filter (MT-BSL/BSC) to the FR-F720-03160 (FR-F740-01800) or more on the inverter output side.

## CAUTION

Especially for long-distance wiring, the inverter may be affected by a charging current caused by the stray capacitances of the wiring, leading to a malfunction of the overcurrent protective function or fast response current limit function or a malfunction or fault of the equipment connected on the inverter output side. If fast-response current limit function malfunctions, disable this function. (For Pr. 156 Stall prevention operation selection, refer to the Instruction Manual (applied).)
For details of Pr. 72 PWM frequency selection ,refer to the Instruction Manual (applied). When using an optional sine wave filter (MT-BSL/ BSC) for the FR-F720-03160 (FR-F740-01800) or more, set "25" in Pr. 72 (2.5kHz).
For explanation of surge voltage suppression filter (FR-ASF-H) and sine wave filter (MT-BSL/BSC), refer to the manual of each option.
(4) Cable size of the control circuit power supply (terminal R1/L11, S1/L21)

Terminal screw size: M4
Cable size: $0.75 \mathrm{~mm}^{2}$ to $2 \mathrm{~mm}^{2}$
Tightening torque: $1.5 \mathrm{~N} \cdot \mathrm{~m}$

### 3.2 Control circuit terminals

## (1) Terminal layout

- Terminal Screw Size: M3.5 Tightening torque: $1.2 \mathrm{~N} \cdot \mathrm{~m}$



## (2) Instructions for wiring of the control circuit terminal

1) Terminals 5, PC and SE are common to the I/O signals and isolated from each other. Do not ground.
2) It is recommended to use the cables of $0.75 \mathrm{~mm}^{2}$ gauge for connection to the control circuit terminals. If the cable gauge used is $1.25 \mathrm{~mm}^{2}$ or more, the front cover may be lifted when there are many cables running or the cables are run improperly, resulting in an operation panel contact fault.
3) The wiring length should be 30 m ( 98.43 feet) maximum.
4) Use two or more parallel micro-signal contacts or twin contacts to prevent a contact faults when using contact inputs since the control circuit input signals are micro-currents.


Micro signal contacts


Twin contacts
5) Use shielded or twisted cables for connection to the control circuit terminals and run them away from the main and power circuits (including the 200V relay sequence circuit).
6) Do not apply a voltage to the contact input terminals (e.g. STF) of the control circuit.
7) Always apply a voltage to the fault output terminals (A, B, C) via a relay coil, lamp, etc.

## 4 PRECAUTIONS FOR USE OF THE INVERTER

The FR-F700 series is a highly reliable product, but incorrect peripheral circuit making or operation/handling method may shorten the product life or damage the product. Before starting operation, always recheck the following items.
(1) Use crimping terminals with insulation sleeve to wire the power supply and motor.
(2) Application of power to the output terminals ( $\mathrm{U}, \mathrm{V}, \mathrm{W}$ ) of the inverter will damage the inverter. Never perform such wiring.
(3) After wiring, wire offcuts must not be left in the inverter.

Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean. When drilling mounting holes in an enclosure etc., take care not to allow chips and other foreign matter to enter the inverter.
(4) Use cables of the size to make a voltage drop $2 \%$ or less.

If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency. Refer to page 8 for the recommended cable sizes.
(5) The overall wiring length should be 500 m ( 1640.4 feet) maximum.

Especially for long distance wiring, the fast response current limit function may decrease or the equipment connected to the secondary side may malfunction or become faulty under the influence of a charging current due to the stray capacity of the wiring. Therefore, note the overall wiring length. (Refer to page 10.)
(6) Electromagnetic wave interference

The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, set the EMC filter valid to minimize interference.
(7) Do not install a power factor correction capacitor, surge suppressor or radio noise filter on the inverter output side. This will cause the inverter to trip or the capacitor, varistor, or arrester to be damaged. If any of the above devices is installed, immediately remove it.
(8) For some short time after the power is switched OFF, a high voltage remains in the smoothing capacitor. When accessing the inverter for inspection, wait for at least 10 minutes after the power supply has been switched OFF, and then make sure that the voltage across the main circuit terminals $\mathrm{P} /+$ and $\mathrm{N} /$ - of the inverter is not more than 30VDC using a tester, etc.
(9) A short circuit or ground fault on the inverter output side may damage the inverter modules.

- Fully check the insulation resistance of the circuit prior to inverter operation since repeated short circuits caused by peripheral circuit inadequacy or a ground fault caused by wiring inadequacy or reduced motor insulation resistance may damage the inverter modules.
- Fully check the to-ground insulation and phase to phase insulation of the inverter output side before power-ON. Especially for an old motor or use in hostile atmosphere, securely check the motor insulation resistance etc.
(10) Do not use the inverter input side magnetic contactor to start/stop the inverter. Always use the start signal (ON/OFF of STF and STR signals) to start/stop the inverter.
(11) Do not apply a voltage higher than the permissible voltage to the inverter I/O signal circuits.

Application of permissible voltage to the inverter I/O signal circuit and incorrect polarity may damage the I/O terminal. Especially check the wiring to prevent the speed setting potentiometer from being connected incorrectly to short terminals 10 E and 5.
(12) Provide electrical and mechanical interlocks for MC1 and MC2 which are used for bypass operation.
When the wiring is incorrect and if there is a bypass operation circuit as shown right, the inverter will be damaged when the power supply is connected to the inverter $\mathrm{U}, \mathrm{V}, \mathrm{W}$ terminals, due to arcs generated at the time of switch-over or chattering caused by a sequence error.

(13) If the machine must not be restarted when power is restored after a power failure, provide a magnetic contactor in the inverter's input side and also make up a sequence which will not switch on the start signal.
If the start signal (start switch) remains on after a power failure, the inverter will automatically restart as soon as the power is restored.
(14) Instructions for overload operation

When performing operation of frequent start/stop of the inverter, increase/decrease in the temperature of the transistor element of the inverter may repeat due to a continuous flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing bound current, starting current, etc. Decreasing current may increase the life. However, decreasing current will result in insufficient torque and the inverter may not start. Therefore, increase the inverter capacity to have enough allowance for current.
(15) Make sure that the specifications and rating match the system requirements.
(16) If electromagnetic noise generated from the inverter causes frequency setting signal to fluctuate and motor rotation speed to be unstable when changing motor speed with analog signal, the following countermeasures are effective.

- Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.
- Run signal cables as far away as possible from power cables (inverter I/O cables).
- Use shield cables as signal cables.
- Install a ferrite core on the signal cable (Example: ZCAT3035-1330 TDK).


## 5 FAILSAFE OF THE SYSTEM WHICH USES THE INVERTER

When a fault occurs, the inverter trips to output a fault signal. However, a fault output signal may not be output at an inverter fault occurrence when the detection circuit or output circuit fails, etc. Although we assure best quality products, provide an interlock which uses inverter status output signals to prevent accidents such as damage to machine when the inverter fails for some reason and at the same time consider the system configuration where failsafe from outside the inverter, without using the inverter, is enabled even if the inverter fails.
(1) Interlock method which uses the inverter status output signals By combining the inverter status output signals to provide an interlock as shown below, an inverter alarm can be detected.

| No | Interlock Method | Check Method | Used Signals | Refer to Page |
| :---: | :--- | :--- | :--- | :--- |
| 1) | Inverter protective <br> function operation | Operation check of an alarm contact <br> Circuit error detection by negative logic | Fault output signal <br> (ALM signal) | Refer to the chapter <br> 4 of the Instruction <br> Manual. |
| 2) | Inverter running status | Operation ready signal check | Operation ready signal <br> (RY signal) | Refer to the chapter <br> 4 of the Instruction <br> Manual. |
| 3) | Inverter running status | Logic check of the start signal and <br> running signal | Start signal <br> (STF signal, STR signal) <br> Running signal (RUN signal) | Refer to the chapter <br> 4 of the Instruction <br> Manual. |
| 4) | Inverter running status | Logic check of the start signal and <br> output current | Start signal <br> (STF signal, STR signal) <br> Output current detection signal <br> (Y12 signal) | Refer to the chapter <br> 4 of the Instruction <br> Manual. |

(2) Backup method outside the inverter

Even if the interlock is provided by the inverter status signal, enough failsafe is not ensured depending on the failure status of the inverter itself. For example, when the inverter CPU fails, even if the interlock is provided using the inverter fault signal, start signal and RUN signal, there is a case where a fault signal is not output and RUN signal is kept output even if an inverter fault occurs.
Provide a speed detector to detect the motor speed and current detector to detect the motor current and consider the backup system such as checking up as below according to the level of importance of the system.

1) Start signal and actual operation check

Check the motor running and motor current while the start signal is input to the inverter by comparing the start signal to the inverter and detected speed of the speed detector or detected current of the current detector. Note that the motor current runs as the motor is running for the period until the motor stops since the inverter starts decelerating even if the start signal turns off. For the logic check, configure a sequence considering the inverter deceleration time. In addition, it is recommended to check the three-phase current when using the current detector.
2) Command speed and actual operation check

Check if there is no gap between the actual speed and commanded speed by comparing the inverter speed command and detected speed of the speed detector.


## 6 PARAMETER LIST

### 6.1 Parameter list

In the initial setting, only the simple mode parameters are displayed.
Set Pr. 160 User group read selection as required.

| Parameter | Name | Initial <br> Value | Setting <br> Range | Remarks |
| :---: | :---: | :---: | :---: | :--- |
| $\mathbf{1 6 0}$ | User group read selection | 0 | 9999 | Only the simple mode parameters can be displayed. |
|  |  |  | Simple mode and extended mode parameters can be <br> displayed. |  |
|  |  |  | Only the parameters registered in the user group can be <br> displayed. |  |

## REMARKS

The parameters marked © are the simple mode parameters.
The parameters marked with $\square$ in the table allow its setting to be changed during operation even if " 0 " (initial value) is set in Pr. 77 Parameter write selection.

| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| (0) 0 | Torque boost | 0 to 30\% | $\begin{gathered} 6 / 4 / 3 / 2 / \\ 1.5 / 1 \% * 1 \end{gathered}$ | 21 | Acceleration/ deceleration time increments | 0, 1 | 0 |
| (0) 1 | Maximum frequency | 0 to 120 Hz | $\underset{{ }^{2} 2}{120 / 60 H z}$ | 22 | Stall prevention | 0 to 120\%, 9999 | 110\% |
| (0) 2 | Minimum frequency | 0 to 120 Hz | OHz |  |  |  |  |
| (0) 3 | Base frequency | 0 to 400 Hz | 60 Hz | 23 | operation level | 0 to 150\%, 9999 | 9999 |
| (0) 4 | Multi-speed setting (high speed) | 0 to 400 Hz | 60 Hz | 23 | compensation factor at double speed | - to 150\%, 9999 | 9999 |
| (0) 5 | Multi-speed setting (middle speed) | 0 to 400 Hz | 30 Hz | 24 to 27 | Multi-speed setting (4 speed to 7 speed) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| (0) 6 | Multi-speed setting (low speed) | 0 to 400 Hz | 10 Hz | 28 | Multi-speed input compensation selection | 0,1 | 0 |
| (0) 7 | Acceleration time | 0 to 3600/360s | $5 \mathrm{~s} / 15 \mathrm{~s} * 3$ |  | Acceleration/ |  |  |
| © 8 | Deceleration time | 0 to 3600/360s | 10s/30s *3 | 29 | deceleration pattern | 0, 1, 2, 3, 6 | 0 |
| (0) 9 | Electronic thermal O/ L relay | $\begin{aligned} & 0 \text { to 500/ } \\ & 0 \text { to } 3600 \mathrm{~A} * 2 \end{aligned}$ | Rated inverter current |  | selection | $\begin{aligned} & 0,2,10,20,100, \\ & 120 / \end{aligned}$ |  |
| 10 | DC injection brake operation frequency | $\begin{aligned} & 0 \text { to } 120 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 3 Hz | 30 | function selection | $\begin{aligned} & 0,1,2,10,11 \\ & 20,21,100,101 \end{aligned}$ | 0 |
| 11 | DC injection brake operation time | 0 to 10s, 8888 | 0.5s | 31 | Frequency jump 1A | $\begin{array}{\|l\|} 120,121 * 2 \\ \hline 0 \text { to } 400 \mathrm{~Hz}, \end{array}$ | 9999 |
| 12 | DC injection brake operation voltage | 0 to 30\% | 4/2/1\% *4 | 32 | Frequency jump 1B | 0 to 400 Hz , 9999 | 9999 |
| 13 | Starting frequency | 0 to 60 Hz | 0.5 Hz |  |  |  |  |
| 14 | Load pattern selection | 0, 1 | 1 | 33 | Frequency jump 2A | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 15 | Jog frequency | 0 to 400 Hz | 5Hz | 34 | Frequency jump 2B | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 16 | Jog acceleration/ deceleration time | 0 to 3600/360s | 0.5s | 35 | Frequency jump 3A | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 17 | MRS input selection | 0, 2 | 0 |  |  |  |  |
| 18 | High speed maximum frequency | 120 to 400 Hz | $120 / 60 \mathrm{~Hz}$ | 36 | Frequency jump 3B | $9999$ | 9999 |
|  |  |  |  | 37 | Speed display | 0, 1 to 9998 | 0 |
| 19 | Base frequency voltage | $\begin{aligned} & 0 \text { to } 1000 \mathrm{~V}, \\ & 8888,9999 \end{aligned}$ | 9999 | 41 | Up-to-frequency sensitivity | 0 to 100\% | 10\% |
| 20 | Acceleration/ deceleration reference frequency | 1 to 400 Hz | 60 Hz | 42 | Output frequency detection | 0 to 400 Hz | 6 Hz |


| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 43 | Output frequency detection for reverse rotation | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 | 75 | Reset selection/ disconnected PU detection/PU stop selection | 0 to 3, 14 to 17, <br> 100 to 103, <br> 114 to 117 *9 | 14 |
| 44 | Second acceleration/ deceleration time | 0 to 3600/360s | 5s | 76 | Fault code output selection | 0, 1, 2 | 0 |
| 45 | Second deceleration time | $\begin{aligned} & 0 \text { to } 3600 / 360 \text { s, } \\ & 9999 \end{aligned}$ | 9999 | 77 | Parameter write selection | 0, 1, 2 | 0 |
| 46 | Second torque boost | 0 to 30\%, 9999 | 9999 |  |  |  |  |
| 47 | Second V/F (base frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & \mathrm{ga99} \end{aligned}$ | 9999 | 78 | Reverse rotation prevention selection | 0, 1, 2 | 0 |
|  | Second stall |  |  | © 79 | Operation mode selection | 0, 1, 2, 3, 4, 6, 7 | 0 |
| 48 | prevention operation current | 0 to 120\% | 110\% | 80 | Motor capacity | ```0.4 to 55kW, 9999/ 0 to 3600kW, 9999 *2``` | 9999 |
| 49 | Second stall prevention operation frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | OHz |  |  |  |  |
| 50 | Second output frequency detection | 0 to 400 Hz | 30 Hz | 90 | Motor constant (R1) | 0 to 50 , 9999/ <br> 0 to $400 \mathrm{~m} \Omega$, <br> 9999 * | 9999 |
| 51 | Second electronic thermal O/L relay | $\begin{array}{\|l\|} \hline 0 \text { to } 500 \mathrm{~A}, \\ 9999 / \\ 0 \text { to } 3600 \mathrm{~A}, \\ 9999 * 2 \end{array}$ | 9999 | 100 | V/F1(first frequency) | $\begin{array}{\|l} 9999 * 2 \\ \hline 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array}$ | 9999 |
|  |  |  |  | 101 | V/F1 (first frequency voltage) | 0 to 1000V | OV |
| 52 | DU/PU main display data selection | 0, 5, 6, 8 to 14, $17,20,23$ to 25 , 50 to 57,100 * 7 | 0 | 102 | voltage) <br> V/F2(second frequency) | $\begin{aligned} & \begin{array}{l} 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array} \end{aligned}$ | 9999 |
| 54 | CA terminal function selection | $\begin{aligned} & 1 \text { to } 3,5,6, \\ & 8 \text { to } 14,17,21, \\ & 24,50,52,53, \\ & 70 * 7 \end{aligned}$ | 1 | 103 | V/F2(second frequency voltage) | 0 to 1000V | OV |
|  |  |  |  | 104 | V/F3(third frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 55 | Frequency monitoring reference | 0 to 400 Hz | 60 Hz | 105 | V/F3(third frequency voltage) | 0 to 1000V | OV |
| 56 | Current monitoring reference | $\begin{array}{\|l\|} 0 \text { to } 500 \mathrm{~A} \\ 0 \text { to } 3600 \mathrm{~A} * 2 \end{array}$ | Rated inverter current | 106 | V/F4(fourth frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
|  | Restart coasting time | $\begin{aligned} & 0,0.1 \text { to } 5 \mathrm{~s}, \\ & 9999 / \\ & 0,0.1 \text { to } 30 \mathrm{~s}, \\ & 9999{ }^{2} 2 \end{aligned}$ | 9999 | 107 | V/F4(fourth frequency voltage) | 0 to 1000V | OV |
| 57 |  |  |  | 108 | V/F5(fifth frequency) | $\begin{array}{\|l} \hline 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \\ \hline \end{array}$ | 9999 |
| 58 | Restart cushion time | 0 to 60s | 1s | 109 | V/F5(fifth frequency voltage) | 0 to 1000V | OV |
| 59 | Remote function selection | $\begin{aligned} & 0,1,2,3,11, \\ & 12,13 \end{aligned}$ | 0 | 117 | PU communication station number | 0 to 31 | 0 |
| (0) 60 | Energy saving control selection | 0, 4, 9 | 0 | 118 | PU communication speed | 48, 96, 192, 384 | 192 |
| 65 | Retry selection | 0 to 5 | 0 |  |  |  |  |
| 66 | Stall prevention | 0 to 400 Hz | 60 Hz | 119 | PU communication stop bit length | 0, 1, 10, 11 | 1 |
|  | starting frequency |  |  | 120 | PU communication parity check | 0, 1, 2 | 2 |
| 67 | Number of retries at fault occurrence | $\begin{aligned} & 0,1 \text { to } 10, \\ & 101 \text { to } 110 \end{aligned}$ | 0 | 121 | Number of PU communication retries | 0 to 10, 9999 | 1 |
| 68 | Retry waiting time | 0 to 10s | 1s |  |  |  |  |
| 69 | Retry count display erase | 0 | 0 | 122 | PU communication check time interval | $\begin{aligned} & 0,0.1 \text { to } 999.8 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 70 | Special regenerative brake duty *8 | 0 to 10\% | 0\% | 123 | PU communication waiting time setting | 0 to 150 ms , 9999 | 9999 |
| 71 | Applied motor | 0, 1, 2, 20 | 0 |  | PU communication CR/LF selection | 0, 1, 2 | 1 |
| 72 | PWM frequency selection | $\begin{aligned} & \hline 0 \text { to } 15 / \\ & 0 \text { to } 6,25 * 2 \end{aligned}$ | 2 | 124 |  |  |  |
| 73 | Analog input selection | 0 to 7,10 to 17 | 1 | © 125 | Terminal 2 frequency setting gain frequency | 0 to 400 Hz | 60Hz |
| 74 | Input filter time constant | 0 to 8 | 1 | © 126 | Terminal 4 frequency setting gain frequency | 0 to 400 Hz | 60 Hz |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 127 | PID control automatic switchover frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 128 | PID action selection | $10,11,20,21$, $50,51,60,61$, $70,71,80,81$, $90,91,100$, $101,110,111$, 120,121 | 10 |
| 129 | PID proportional band | $\begin{aligned} & 0.1 \text { to } 1000 \% \text {, } \\ & 9999 \end{aligned}$ | 100\% |
| 130 | PID integral time | $\begin{aligned} & 0.1 \text { to } 3600 \mathrm{~s} \text {, } \\ & 9999 \end{aligned}$ | 1s |
| 131 | PID upper limit | $\begin{aligned} & \hline 0 \text { to 100\%, } \\ & 9999 \end{aligned}$ | 9999 |
| 132 | PID lower limit | $\begin{aligned} & 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 |
| 133 | PID action set point | $\begin{aligned} & 0 \text { to 100\%, } \\ & 9999 \end{aligned}$ | 9999 |
| 134 | PID differential time | $\begin{aligned} & 0.01 \text { to } 10.00 \mathrm{~s} \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 135 | Electronic bypass sequence selection | 0, 1 | 0 |
| 136 | MC switchover interlock time | 0 to 100s | 1s |
| 137 | Start waiting time | 0 to 100s | 0.5s |
| 138 | Bypass selection at a fault | 0, 1 | 0 |
| 139 | Automatic switchover frequency from inverter to bypass operation | 0 to 60Hz, 9999 | 9999 |
| 140 | Backlash acceleration stopping frequency | 0 to 400 Hz | 1 Hz |
| 141 | Backlash acceleration stopping time | 0 to 360s | 0.5s |
| 142 | Backlash deceleration stopping frequency | 0 to 400 Hz | 1 Hz |
| 143 | Backlash deceleration stopping time | 0 to 360s | 0.5s |
| 144 | Speed setting switchover | $\begin{aligned} & 0,2,4,6,8,10, \\ & 102,104,106, \\ & 108,110 \end{aligned}$ | 4 |
| 145 | PU display language selection | 0 to 7 | 1 |
| 147 | Acceleration/ deceleration time switching frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 148 | Stall prevention level at $0 V$ input | 0 to 120\% | 110\% |
| 149 | Stall prevention level at 10 V input | 0 to 120\% | 120\% |
| 150 | Output current detection level | 0 to 120\% | 110\% |
| 151 | Output current detection signal delay time | 0 to 10s | Os |
| 152 | Zero current detection level | 0 to 150\% | 5\% |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 153 | Zero current detection time | 0 to 10s | 0.5 s |
| 154 | Voltage reduction selection during stall prevention operation | 0, 1 | 1 |
| 155 | RT signal function validity condition selection | 0, 10 | 0 |
| 156 | Stall prevention operation selection | $\begin{aligned} & 0 \text { to } 31,100, \\ & 101 \end{aligned}$ | 0 |
| 157 | OL signal output timer | 0 to 25s, 9999 | Os |
| 158 | AM terminal function selection | 1 to $3,5,6$, <br> 8 to $14,17,21$, <br> $24,50,52,53,70$ <br> ${ }_{* 7}$ | 1 |
| 159 | Automatic switchover frequency range from bypass to inverter operation | 0 to 10Hz, 9999 | 9999 |
| ©160 | User group read selection | 0, 1, 9999 | 0 |
| 161 | Frequency setting/ key lock operation selection | 0, 1, 10, 11 | 0 |
| 162 | Automatic restart after instantaneous power failure selection | 0, 1, 10, 11 | 0 |
| 163 | First cushion time for restart | 0 to 20s | 0s |
| 164 | First cushion voltage for restart | 0 to 100\% | 0\% |
| 165 | Stall prevention operation level for restart | 0 to 120\% | 110\% |
| 166 | Output current detection signal retention time | 0 to 10s, 9999 | 0.1s |
| 167 | Output current detection operation selection | 0, 1, 10, 11 | 0 |
| 168 | Parameter for manufacturer setting. Do not set. |  |  |
| 169 |  |  |  |
| 170 | Watt-hour meter clear | 0, 10, 9999 | 9999 |
| 171 | Operation hour meter clear | 0,9999 | 9999 |
| 172 | User group registered display/ batch clear | 9999, (0 to 16) | 0 |
| 173 | User group registration | 0 to 999, 9999 | 9999 |
| 174 | User group clear | 0 to 999, 9999 | 9999 |
| 178 | STF terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14 \text {, } \\ & 16,24,25,50, \\ & 51,60,62,64 \text { to } \\ & 67,70 \text { to } 72,77, \\ & 78,9999 \end{aligned}$ | 60 |


| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 179 | STR terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14, \\ & 16,24,25,50, \\ & 51,61,62,64 \text { to } \\ & 67,70 \text { to } 72,77, \\ & 78,9999 \end{aligned}$ | 61 | 242 | Terminal 1 added compensation amount (terminal 2) | 0 to 100\% | 100\% |
|  |  |  |  | 243 | Terminal 1 added compensation amount (terminal 4) | 0 to 100\% | 75\% |
| 180 | RL terminal function | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14, \\ & 16,24,25,50, \\ & 51,62,64 \text { to } 67, \\ & 70 \text { to } 72,77,78, \\ & 9999 \end{aligned}$ | 0 |  |  |  |  |
| 181 | selection |  | 0 | 244 | Cooling fan operation selection | 0, 1 | 1 |
| 181 | selection |  | 1 | 245 | Rated slip | 0 to 50\%, 9999 | 9999 |
| 182 | RH terminal function selection |  | 2 | 246 | Slip compensation time constant | 0.01 to 10s | 0.5s |
| 183 | RT terminal function selection |  | 3 | 247 | Constant-power range slip compensation selection | 0,9999 | 9999 |
| 184 | AU terminal function selection | 0 to 8,10 to 14,$16,24,25,50$,51,62 to 67,70to $72,77,78$,9999 | 4 |  |  |  |  |
|  |  |  |  | 250 | Stop selection | 0 to 100s, 1000 to 1100s, 8888, 9999 | 9999 |
| 185 | JOG terminal function selection | 0 to 8,10 to 14 , 16, 24, 25, 50, 51, 62, 64 to 67, 70 to $72,77,78$, 9999 | 5 | 251 | Output phase loss protection selection | 0, 1 | 1 |
| 186 | CS terminal function selection |  | 6 | 252 | Override bias | 0 to 200\% | 50\% |
|  | MRS terminal |  | 24 | 253 | Override gain | 0 to 200\% | 150\% |
| 187 | function selection |  |  | 255 | Life alarm status display | (0 to 15) | 0 |
| 188 | STOP terminal function selection RES terminal |  | 25 | 256 | Inrush current limit circuit life display | (0 to 100\%) | 100\% |
| 189 | function selection |  | 62 | 257 | Control circuit capacitor life display | (0 to 100\%) | 100\% |
| 190 | RUN terminal function selection | 0 to $5,7,8$,10 to $19,25,26$,45 to $54,64,67$,70 to $79,85,90$ to$96,98,99$,100 to 105,107,108,110 to 116,125,126,145 to 154,164,167,170 to 179,185,190 to 196,$198,199,9999$$\times 10$ | 0 | 258 | Main circuit capacitor life display | (0 to 100\%) | 100\% |
| 191 | SU terminal function selection |  | 1 | 259 | Main circuit capacitor life measuring | 0, 1 | 0 |
| 192 | IPF terminal function selection |  | 2 | 260 | PWM frequency automatic switchover | 0, 1 | 1 |
|  |  |  | 3 | 261 | Power failure stop selection | 0, 1, 2, 21, 22 | 0 |
| 193 | OL terminal function selection |  |  | 262 | Subtracted frequency at deceleration start | 0 to 20 Hz | 3 Hz |
| 194 | FU terminal function selection |  | 4 |  |  |  |  |
| 195 |  |  | 99 | 263 | Subtraction starting frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \\ & \hline \end{aligned}$ | 60Hz |
|  | ABC1 terminal function selection | 0 to $5,7,8$, 10 to $19,25,26$, 45 to $54,64,67$, 70 to $79,85,90$, 91, 94 to 96,98 , 99,100 to 105 , 107, 108, 110 to 116,125 , 126, 145 to 154, 164, 167, 170 to 179, 185, 190, 191, 194 to 196,198, 199, 9999 *10 |  | 264 | Power-failure deceleration time 1 | 0 to 3600/360s | 5s |
|  |  |  |  | 265 | Power-failure deceleration time 2 | $\begin{aligned} & 0 \text { to } 3600 / 360 \mathrm{~s} \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 196 | ABC2 terminal function selection |  | 9999 | 266 | Power failure deceleration time switchover frequency | 0 to 400 Hz | 60Hz |
|  |  |  |  | 267 | Terminal 4 input selection | 0, 1, 2 | 0 |
|  |  |  |  | 268 | Monitor decimal digits selection | 0, 1, 9999 | 9999 |
| 232 | Multi-speed setting (8 speed to 15 speed) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 | 269 | Parameter for manufacturer setting. |  |  |
| $\begin{gathered} \text { to } \\ 239 \end{gathered}$ |  |  |  | 296 | Password lock level | $\begin{aligned} & 0 \text { to } 6,99, \\ & 100 \text { to 106, } \\ & 199,9999 \end{aligned}$ | 9999 |
| 240 | Soft-PWM operation selection | 0, 1 | 1 | 297 | Password lock/ unlock | $\begin{array}{\|l\|} \hline(0 \text { to } 5), \\ 1000 \text { to } 9998, \\ 9999 \end{array}$ | 9999 |
| 241 | Analog input display unit switchover | 0, 1 | 0 |  |  |  |  |


| Parameters | Name | Setting Range | Initial <br> Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 299 | Rotation direction detection selection at restarting | 0, 1, 9999 | 9999 | 539 | Modbus-RTU communication check time interval | $\begin{aligned} & 0 \text { to } 999.8 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 331 | RS-485 communication station number | 0 to 31 <br> (0 to 247) | 0 | 549 | Protocol selection | 0, 1 | 1 |
|  |  |  |  | 550 | NET mode operation command source selection | 0, 1, 9999 | 9999 |
| 332 | RS-485 communication speed | $\begin{aligned} & 3,6,12,24, \\ & 48,96,192,384 \end{aligned}$ | 96 | 551 | PU mode operation command source selection | 1, 2 | 2 |
| 333 | RS-485 communication stop bit length | 0, 1, 10, 11 | 1 | 553 | selection | $\begin{aligned} & 0 \text { to 100.0\%, } \\ & 9999 \end{aligned}$ | 9999 |
| 334 | RS-485 communication parity check selection | 0, 1, 2 | 2 | 554 | PID signal operation selection | 0 to 3, 10 to 13 | 0 |
|  |  |  |  | 555 | Current average time | 0.1 to 1.0s | 1s |
| 335 | RS-485 communication retry count | 0 to 10, 9999 | 1 | 556 | Data output mask time | 0.0 to 20.0s | Os |
|  |  |  |  | 557 | Current average value monitor signal output reference current | $\begin{aligned} & 0 \text { to 500A } \\ & 0 \text { to } 3600 \mathrm{~A} * 2 \end{aligned}$ | Rated inverter current |
| 336 | RS-485 communication check time interval | $\begin{aligned} & 0 \text { to } 999.8 \mathrm{~s}, \\ & 9999 \end{aligned}$ | Os |  |  |  |  |
|  |  |  |  | 563 | Energization time carrying-over times | (0 to 65535) | 0 |
| 337 | RS-485 communication waiting time setting | 0 to 150 ms, 9999 | 9999 | 564 | Operating time carrying-over times | (0 to 65535) | 0 |
| 338 | Communication operation command source | 0, 1 | 0 | 570 | Multiple rating setting | 0, 1 | 0 |
|  |  |  |  | 571 | Holding time at a start | $\begin{aligned} & 0.0 \text { to } 10.0 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 339 | Communication speed command source | 0, 1, 2 | 0 | 573 | start <br> 4mA input check selection | 9999 | 9999 |
| 340 | Communication startup mode selection | 0, 1, 2, 10, 12 | 0 | 575 | Output interruption detection time | $\begin{aligned} & 0 \text { to 3600s, } \\ & 9999 \end{aligned}$ | 1s |
| 341 | RS-485 <br> communication CR/ <br> LF selection | 0, 1, 2 | 1 | 576 | Output interruption detection level | 0 to 400 Hz | OHz |
|  |  |  |  | 577 | Output interruption cancel level | 900 to 1100\% | 1000\% |
| 342 | Communication EEPROM write selection | 0, 1 | 0 | 578 | Auxiliary motor operation selection | 0 to 3 | 0 |
| 343 | Communication error count |  | 0 | 579 | Motor connection function selection | 0 to 3 | 0 |
| 414 | PLC function operation selection | 0, 1 | 0 | 580 | MC switching interlock time | 0 to 100s | 1s |
| 415 | Inverter operation lock mode setting | 0, 1 | 0 | 581 | Start waiting time | 0 to 100s | 1s |
|  |  |  |  | 582 | Auxiliary motor connection-time deceleration time | $\begin{aligned} & 0 \text { to } 3600 / 360 \text { s, } \\ & 9999 \end{aligned}$ | 1s |
| 495 | Remote output selection | 0, 1, 10, 11 | 0 |  |  |  |  |
| 496 | Selection ${ }^{\text {Remote output data } 1}$ | 0 to 4095 | 0 | 583 | Auxiliary motor disconnection-time acceleration time | $\begin{aligned} & 0 \text { to } 3600 / 360 \mathrm{~s} \text {, } \\ & 9999 \end{aligned}$ | 1s |
| 497 | Remote output data 2 | 0 to 4095 | 0 | 584 | Auxiliary motor 1 starting frequency | 0 to 400 Hz | 60Hz |
| 498 | PLC function flash memory clear | 0 to 9999 | 0 |  |  |  |  |
| 502 | Stop mode selection at communication error | 0 to 3 | 0 | 585 | Auxiliary motor 2 starting frequency | 0 to 400 Hz | 60Hz |
|  |  |  |  | 586 | Auxiliary motor 3 starting frequency | 0 to 400 Hz | 60Hz |
| 503 | Maintenance timer | 0 (1 to 9998) | 0 | 587 | Auxiliary motor 1 stopping frequency | 0 to 400 Hz | 0Hz |
| 504 | Maintenance timer alarm output set time | 0 to 9998, 9999 | 9999 |  |  |  |  |
| 505 | Speed setting reference |  | 60 Hz | 588 | Auxiliary motor 2 stopping frequency | 0 to 400 Hz | OHz |
|  |  | 1 to 120 Hz |  | 589 | Auxiliary motor 3 stopping frequency | 0 to 400 Hz | 0Hz |
| $\begin{array}{\|c} \hline 506 \text { to } \\ 515 \end{array}$ | Parameter 1 to 10 for user | 0 to 65535 | 0 | 590 | Auxiliary motor start detection time | 0 to 3600s | 5 s |
| 522 | Output stop frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |


| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 591 | Auxiliary motor stop detection time | 0 to 3600s | 5 s | 779 | Operation frequency during communication error | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 611 | Acceleration time at a restart | $\begin{aligned} & 0 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 5/15s *2 |  |  |  |  |
|  |  |  |  | 799 | Pulse increment setting for output power | $0.1 \mathrm{kWh}, 1 \mathrm{kWh}$, 10kWh, 100kWh, 1000 kWh | 1kWh |
| 653 | Speed smoothing control | 0 to 200\% | 0 |  |  |  |  |
| 654 | Speed smoothing cutoff frequency | 0 to 120 Hz | 20 Hz |  |  |  |  |
|  |  |  |  | $\begin{gathered} 826 \text { to } \\ 865 \end{gathered}$ | Parameter 11 to 50 for user | 0 to 65535 | 0 |
| 665 | Regeneration avoidance frequency gain | 0 to 200\% | 100\% |  |  |  |  |
|  |  |  |  | 867 | AM output filter | 0 to 5s | 0.01s |
| 753 | Second PID action selection | $10,11,20,21$,$50,51,60,61$,$70,71,80,81$,$90,91,100$,$101,110,111$,$120,121,9999$ | 9999 | 869 | Current output filter | 0 to 5s | 0.02s |
|  |  |  |  | 870 | Speed detection hysteresis | 0 to 5 Hz | OHz |
|  |  |  |  | 872 | Input phase loss protection selection | 0, 1 | 0 |
|  |  |  |  | 882 | Regeneration avoidance operation selection | 0, 1, 2 | 0 |
| 754 | Second PID control automatic switchover frequency | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |
|  |  |  |  | 883 | Regeneration avoidance operation level | 300 to 800 V | 380VDC/ <br> 760VDC |
| 755 | Second PID action set point | $\begin{aligned} & \hline 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |
| 756 | Second PID proportional band | $\begin{aligned} & 0.1 \text { to } 1000 \%, \\ & 9999 \end{aligned}$ | 100\% | 884 | Regeneration avoidance at deceleration detection sensitivity | 0 to 5 | 0 |
| 757 | Second PID integral time | $\begin{aligned} & 0.1 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 1s |  |  |  |  |
|  |  |  |  | 885 | Regeneration avoidance compensation frequency limit value | 0 to 30Hz, 9999 | 6 Hz |
| 758 | Second PID differential time | $\begin{aligned} & 0.01 \text { to } 10.00 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |
| 759 | PID unit selection | 0 to 43, 9999 | 9999 |  |  |  |  |
| 760 | Pre-charge fault selection | 0,1 | 0 | 886 | Regeneration avoidance voltage gain | 0 to 200\% | 100\% |
| 761 | Pre-charge ending level | $\begin{aligned} & 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 | 888 | Free parameter 1 | 0 to 9999 | 9999 |
|  |  |  |  | 889 | Free parameter 2 | 0 to 9999 | 9999 |
| 762 | time | $9999$ | 9999 | 891 | Cumulative power monitor digit shifted times | 0 to 4, 9999 | 9999 |
| 763 | Pre-charge upper detection level | $\begin{aligned} & 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |
|  |  |  |  | 892 | Load factor | 30 to 150\% | 100\% |
| 764 | Pre-charge time limit | $9999$ | 9999 | 893 | Energy saving monitor reference (motor capacity) | 0.1 to $55 \mathrm{~kW} /$ 0 to 3600 kW *2 | LD/SLD value of applied motor capacity |
| 765 | Second pre-charge fault selection | 0, 1 | 0 |  |  |  |  |
| 766 | Second pre-charge ending level | $\begin{aligned} & 0 \text { to 100\%, } \\ & 9999 \end{aligned}$ | 9999 | 894 | Control selection during commercial power-supply operation | 0, 1, 2, 3 | 0 |
| 767 | Second pre-charge ending time | $\begin{aligned} & 0 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |  |  |  |  |
| 768 | Second pre-charge upper detection level | $\begin{aligned} & 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 | 895 | Power saving rate reference value | 0, 1, 9999 | 9999 |
| 769 | Second pre-charge time limit | $\begin{aligned} & 0 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 | 896 | Power unit cost | 0 to 500, 9999 | 9999 |
| 774 | PU/DU monitor selection 1 | $\begin{aligned} & 1 \text { to } 3,5,6, \\ & 8 \text { to } 14,17,20, \\ & 23 \text { to } 25, \\ & 40 \text { to } 42, \\ & 50 \text { to } 57,100, \\ & 9999{ }^{* 7} \end{aligned}$ | 9999 | 897 | Power saving monitor average time | $\begin{aligned} & \hline \begin{array}{l} 0,1 \text { to } 1000 \mathrm{~h}, \\ 9999 \end{array} \\ & \hline \end{aligned}$ | 9999 |
| 775 | PU/DU monitor selection 2 |  | 9999 | 898 | Power saving cumulative monitor clear | 0, 1, 10, 9999 | 9999 |
| 776 | PU/DU monitor selection 3 |  | 9999 | 899 | Operation time rate (estimated value) | $\begin{aligned} & 0 \text { to } 100 \% \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 777 | 4mA input fault operation frequency | $\begin{array}{\|l\|} \hline 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array}$ | 9999 | $\begin{aligned} & \text { C0 *6 } \\ & (900) \end{aligned}$ | CA terminal calibration | - | - |
| 778 | Current input check filter | 0 to10s | Os | $\begin{gathered} \text { C1*6 } \\ \text { (901) } \end{gathered}$ | AM terminal calibration | - | - |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { C2 *6 } \\ & \mathbf{( 9 0 2 )} \end{aligned}$ | Terminal 2 frequency setting bias frequency | 0 to 400 Hz | 0Hz |
| $\begin{aligned} & \text { C3 *6 } \\ & \text { (902) } \end{aligned}$ | Terminal 2 frequency setting bias | 0 to 300\% | 0\% |
| $\begin{aligned} & 125 * 6 \\ & (903) \end{aligned}$ | Terminal 2 frequency setting gain frequency | 0 to 400 Hz | 60 Hz |
| $\begin{aligned} & \text { C4*6 } \\ & \text { (903) } \end{aligned}$ | Terminal 2 frequency setting gain | 0 to 300\% | 100\% |
| $\begin{gathered} C 5 * 6 \\ (904) \end{gathered}$ | Terminal 4 frequency setting bias frequency | 0 to 400 Hz | OHz |
| $\begin{gathered} \text { C6*6 } \\ \mathbf{( 9 0 4 )} \end{gathered}$ | Terminal 4 frequency setting bias | 0 to 300\% | 20\% |
| $\begin{aligned} & 126 * 6 \\ & (905) \end{aligned}$ | Terminal 4 frequency setting gain frequency | 0 to 400 Hz | 60 Hz |
| $\begin{aligned} & \hline \text { C7 *6 } \\ & (905) \end{aligned}$ | Terminal 4 frequency setting gain | 0 to 300\% | 100\% |
| $\begin{aligned} & \text { C8 *6 } \\ & \mathbf{( 9 3 0 )} \\ & \hline \end{aligned}$ | Current output bias signal | 0 to 100\% | 0\% |
| $\begin{aligned} & \text { C9*6 } \\ & (930) \end{aligned}$ | Current output bias current | 0 to 100\% | 0\% |
| $\begin{aligned} & \text { C10*6 } \\ & \text { (931) } \end{aligned}$ | Current output gain signal | 0 to 100\% | 100\% |
| $\begin{aligned} & \text { C11*6 } \\ & \text { (931) } \end{aligned}$ | Current output gain current | 0 to 100\% | 100\% |
| $\begin{gathered} \hline \text { © C42*6 } \\ \text { (934) } \end{gathered}$ | PID display bias coefficient | $\begin{aligned} & 0 \text { to 500.00, } \\ & 9999 \end{aligned}$ | 9999 |
| $\begin{array}{\|c\|} \hline \text { © C43*6 } \\ (934) \end{array}$ | PID display bias analog value | 0 to 300.0\% | 20\% |
| $\begin{array}{\|l\|} \hline \text { © C44*6 } \\ (935) \end{array}$ | PID display gain coefficient | $\begin{aligned} & 0 \text { to } 500.00, \\ & 9999 \end{aligned}$ | 9999 |
| $\begin{array}{\|c\|} \hline \text { © C45 *6 } \\ \mathbf{( 9 3 5 )} \\ \hline \end{array}$ | PID display gain analog value | 0 to 300.0\% | 100\% |
| 989 | Parameter copy alarm release | 10/100 *2 | 10/100 *2 |
| 990 | PU buzzer control | 0, 1 | 1 |
| 991 | PU contrast adjustment | 0 to 63 | 58 |
| 997 | Fault initiation | 16 to 18, 32 to $34,48,49$, 64,80 to 82,96, $112,128,129$, $144,145,160$, 161,162, 164 to 168, 176 to 179, 192 to 194, 196 to 199, 228 to 230,241, 242,245 to 247, 253,9999 | 9999 |
| © 999 | Automatic parameter setting | $\begin{aligned} & 1,2,10,11,20, \\ & 21,30,31, \\ & 9999 \end{aligned}$ | 9999 |
| Pr.CL | Parameter clear | 0, 1 | 0 |
| ALLC | All parameter clear | 0, 1 | 0 |
| Er.CL | Faults history clear | 0, 1 | 0 |


| Parameters | Name | Setting Range | Initial <br> Value |
| :--- | :--- | :---: | :---: |
| PCPY | Parameter copy | $0,1,2,3$ | 0 |
| Pr.CH | Initial value change <br> list | - | - |
| AUTO | Automatic parameter <br> setting | - | - |

*1 Differ according to capacities.
6\%: FR-F720-00046, FR-F740-00023
4\%: FR-F720-00077 to 00167, FR-F740-00038 to 00083
3\%: FR-F720-00250 and 00340, FR-F740-00126 and 00170
2\%: FR-F720-00490 to 01540, FR-F740-00250 to 00770
1.5\%:FR-F720-01870 and 02330, FR-F740-00930 and 01160
$1 \%$ : FR-F720-03160 or more, FR-F740-01800 or more
*2 Differ according to capacities
FR-F720-02330 or less / FR-F720-03160 or more
FR-F740-01160 or less / FR-F740-01800 or more
*3 Differ according to capacities.
FR-F720-00340 or less / FR-F720-00490 or more FR-F740-00170 or less / FR-F740-00250 or more
*4 Differ according to capacities.
4\%: FR-F720-00340 or less, FR-F740-00170 or less
2\%: FR-F720-00490 to 02330, FR-F740-00250 to 01160
1\%: FR-F720-03160 or more, FR-F740-01800 or more
*5 Differs according to the voltage class. ( 200 V class/400V class).
6 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04/FR-PU07).
7 Setting of "9" can be made for the FR-F720-03160 (FR-F74001800) or more.
*8 Setting can be made for the FR-F720-03160 (FR-F740-01800) or more.
*9 Setting of "100 to 103", "114 to 117" can be made for the FR-F72003160 (FR-F740-01800) or more
*10 Setting of "7, 107" can be made for the FR-F720-03160 (FR-F74001800) or more.

## 7 TROUBLESHOOTING

When a fault occurs in the inverter, the inverter trips and the PU display automatically changes to any of the following fault or alarm indications.
If the fault does not correspond to any of the following faults or if you have any other problem, please contact your sales representative.

- Retention of fault output signal $\qquad$ When the magnetic contactor (MC) provided on the input side of the inverter is opened when a fault occurs, the inverter's control power will be lost and the fault output will not be held.
- Fault or alarm indication $\qquad$ When a fault or alarm occurs, the operation panel display automatically switches to the fault or alarm indication.
- Resetting method $\qquad$ When a fault occurs, the inverter output is kept stopped. Unless reset, therefore, the inverter cannot restart. (Refer to page 20.)
- When any fault occurs, take the appropriate corrective action, then reset the inverter, and resume operation. Not doing so may lead to the inverter fault and damage.

Inverter fault or alarm indications are roughly categorized as below.
(1) Error message

A message regarding operational fault and setting fault by the operation panel (FR-DU07) and parameter unit (FR-PU07/FR-PU04) is displayed. The inverter does not trip.
(2) Warnings

The inverter does not trip even when a warning is displayed. However, failure to take appropriate measures will lead to a fault.
(3) Alarm

The inverter does not trip. You can also output an alarm signal by making parameter setting.
(4) Fault

When a fault occurs, the inverter trips and a fault signal is output.

### 7.1 Reset method of protective function

The inverter can be reset by performing any of the following operations. Note that the internal thermal integrated value of the electronic thermal relay function and the number of retries are cleared (erased) by resetting the inverter. Inverter recovers about 1s after the reset is released.

Operation 1: ..... Using the operation panel, press $\left(\frac{\text { STOP }}{\text { RESEI }}\right)$ to reset the inverter.
(This may only be performed when a fault occurs (Refer to the Instruction Manual (applied) for fault.))


Operation 2:...... Switch power off once. After the indicator of the operation panel turns OFF, switch it ON again.


Operation 3: ..... Turn ON the reset signal (RES) for more than 0.1 s . (If the RES signal is kept ON, "Err." appears (flickers) to indicate that the inverter is in a reset status.)


REMARKS

- When a fault occurs during PLC function, turning ON of X51 signal can release fault without interrupting PLC function. (Refer to FR-F700 PLC function programming manual)


## 7．2 List of fault or alarm display

| Operation Panel Indication |  |  | Name | Fault Data Code |
| :---: | :---: | :---: | :---: | :---: |
|  | E－－－ | E－－－ | Faults history |  |
|  | HOT | HOLD | Operation panel lock |  |
|  | 6016 | LOCd | Password locked | － |
|  | $\begin{array}{rrr} \hline 1 & \text { to } \\ E_{r} & \end{array}$ | Er1 to 4 | Parameter write error | － |
|  | $\begin{array}{rl:l} \hline-E & \text { to } \\ r E G \end{array}$ | rE1 to 4 | Copy operation error | － |
|  | Err． | Err． | Error |  |
|  |  | OL | Stall prevention （evercurrent） |  |
|  | 01 | oL | Stall prevention （overvoltage） |  |
|  | rb | RB | Regenerative brake prealarm | － |
|  | 「H＇ | TH | Electronic thermal relay function prealarm |  |
|  | PG | PS | PU stop |  |
|  | 7ir | MT | Maintenance signal output | － |
|  | EP | CP | Parameter copy |  |
|  | $F{ }_{6}$ | FN | Fan alarm |  |
| $\left\lvert\, \begin{aligned} & \stackrel{\rightharpoonup}{\vec{u}} \\ & \stackrel{\rightharpoonup}{山} \end{aligned}\right.$ | ESIC | E．OC1 | Overcurrent trip during acceleration | $\begin{array}{\|c\|} \hline 16 \\ \text { (H10) } \\ \hline \end{array}$ |
|  | ERE® | E．OC2 | Overcurrent trip during constant speed | $\begin{array}{\|c\|c\|} \hline 17 \\ \hline \text { (H11) } \\ \hline \end{array}$ |
|  | ESE | E．OC3 | Overcurrent trip during deceleration or stop | $\begin{aligned} & 18 \\ & (H 12) \end{aligned}$ |
|  | E．OU | E．OV1 | Regenerative overvoltage trip during acceleration | $\begin{array}{\|c} \hline 32 \\ \text { (H20) } \\ \hline \end{array}$ |
|  | Eイいご | E．OV2 | Regenerative overvoltage trip during constant speed | $\begin{gathered} 33 \\ \hline(H 21) \\ \hline \end{gathered}$ |
|  | E感い | E．OV3 | Regenerative overvoltage trip during deceleration or stop | $\begin{gathered} 34 \\ \text { (H22) } \end{gathered}$ |
|  | Erim | E．THT | Inverter overload trip （electronic thermal relay function） | $\begin{gathered} 48 \\ (H 30) \end{gathered}$ |
|  | E． 40 | E．THM | Motor overload trip （electronic thermal relay function） | $\begin{array}{\|c\|} \hline 49 \\ (H 31) \end{array}$ |
|  | E．Fin | E．FIN | Fin overheat | $\begin{gathered} 64 \\ (\mathrm{H} 40) \end{gathered}$ |
|  | E．tr | E．IPF | Instantaneous power failure | $\begin{array}{\|c} \hline 80 \\ \hline \text { (H50) } \\ \hline \end{array}$ |
|  | E．Lui＇ | E．UVT | Undervoltage | $\begin{gathered} 81 \\ (H 51) \end{gathered}$ |


| Operation Panel Indication |  |  | Name | Fault Data Code |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \stackrel{\rightharpoonup}{\vec{J}} \\ & \stackrel{\pi}{\widetilde{2}} \end{aligned}$ | E． 1 | E．ILF＊ | Input phase loss | $\begin{gathered} 82 \\ \text { (H52) } \end{gathered}$ |
|  | ER15 | E．OLT | Stall prevention stop | $\begin{gathered} 96 \\ (H 60) \end{gathered}$ |
|  | E．Eir | E．GF | Output side ground fault overcurrent | $\begin{gathered} 128 \\ \text { (H80) } \\ \hline \end{gathered}$ |
|  | E． | E．LF | Output phase loss | $\begin{gathered} 129 \\ \text { (H81) } \end{gathered}$ |
|  | E．BHi | E．OHT | External thermal relay operation ${ }^{2}$ | $\begin{gathered} 144 \\ (\mathrm{H} 90) \end{gathered}$ |
|  | EッF！ | E．PTC＊ | PTC thermistor operation | $\begin{gathered} 145 \\ (\mathrm{H} 91) \end{gathered}$ |
|  | E．OF\％ | E．OPT | Option fault | $\begin{gathered} 160 \\ \text { (HAO) } \end{gathered}$ |
|  | E日R： <br> EDPO | $\begin{aligned} & \text { E.OP1 } \\ & \text { E.OP2 } \end{aligned}$ | Communication option fault （e．g．communication error） | $\begin{gathered} 161 \\ \text { (HA1) } \\ 162 \\ \text { (HA2) } \end{gathered}$ |
|  | $\begin{array}{ll} E & i \\ E & \Xi \end{array}$ | $\begin{aligned} & \text { E. } 1 \\ & \text { E. } 2 \end{aligned}$ | Option fault <br> （e．g．connection or contact fault） | $\begin{gathered} 241 \\ \text { (HF1) } \\ 242 \\ \text { (HF2) } \\ \hline \end{gathered}$ |
|  | E．FIE | E．PE | Parameter storage device fault | $\begin{gathered} 176 \\ \hline \text { (HBO) } \end{gathered}$ |
|  | E．F゙心G | E．PUE | PU disconnection | $\begin{gathered} 177 \\ \text { (HB1) } \end{gathered}$ |
|  | $E . \mathrm{EI}$ | E．RET | Retry count excess | $\begin{gathered} 178 \\ \hline \text { (HB2) } \\ \hline \end{gathered}$ |
|  | EGEこ | E．PE2＊ | Parameter storage device fault | $\begin{gathered} 179 \\ \text { (HB3) } \\ \hline \end{gathered}$ |
|  |  | $\begin{array}{\|c} \text { E. } 5 \\ \text { E. } 6 \\ \text { E. } 7 \\ \text { E.CPU } \end{array}$ | CPU fault | 245 （HF5） 246 （HF6） 247 （HF7） 192 （HCO） |
|  | EGE | E．CTE | Operation panel power supply short circuit，RS－485 terminal power supply short circuit | $\begin{gathered} 193 \\ (H C 1) \end{gathered}$ |
|  | E．ローツ | E．P24 | 24VDC power output short circuit | $\begin{gathered} 194 \\ (\mathrm{HC} 2) \end{gathered}$ |
|  | E．Coid | E．CDO＊ | Output current detection value exceeded | $\begin{gathered} 196 \\ \text { (HC4) } \end{gathered}$ |
|  | E． $\mathrm{Bl}_{6}$ | E．IOH＊ | Inrush current limit circuit fault | $\begin{gathered} 197 \\ (H C 5) \end{gathered}$ |
|  | E．GEr | E．SER＊ | Communication fault （inverter） | $\begin{gathered} 198 \\ \hline \text { (HC6) } \end{gathered}$ |
|  | E．FiE | E．AIE＊ | Analog input fault | $\begin{aligned} & 199 \\ & (\mathrm{HC} 7) \end{aligned}$ |
|  | E！ロ | E．PID＊ | PID signal fault | $\begin{gathered} 230 \\ (\mathrm{HE}) \end{gathered}$ |
|  | E． | E．BE | Brake transistor alarm detection／internal circuit error | $\begin{gathered} 112 \\ (\mathrm{H} 70) \end{gathered}$ |
|  | $E .13$ | E． 13 | Internal circuit fault | $\begin{gathered} 253 \\ \text { (HFD) } \end{gathered}$ |
|  | $E .10$ | E．PCH＊ | Pre－charge fault | $\begin{aligned} & 229 \\ & \text { (HE5) } \end{aligned}$ |
|  | E．E＇ | E．LCl＊ | 4 mA input fault | $\begin{gathered} 228 \\ \hline \text { (HE4) } \end{gathered}$ |

[^1]
## Appendix 1 Instructions for compliance with the EU Directives

The EU Directives are issued to standardize different national regulations of the EU Member States and to facilitate free movement of the equipment, whose safety is ensured, in the EU territory.
Since 1996, compliance with the EMC Directive that is one of the EU Directives has been legally required. Since 1997, compliance with the Low Voltage Directive, another EU Directive, has been also legally required. When a manufacturer confirms its equipment to be compliant with the EMC Directive and the Low Voltage Directive, the manufacturer must declare the conformity and affix the CE marking.

## - The authorized representative in the EU

The authorized representative in the EU is shown below.
Name: Mitsubishi Electric Europe B.V.
Address: Gothaer Strasse 8, 40880 Ratingen, Germany

- Note

We declare that this inverter conforms with the EMC Directive in industrial environments and affix the CE marking on the inverter. When using the inverter in a residential area, take appropriate measures and ensure the conformity of the inverter used in the residential area.

## (1) EMC Directive

We declare that this inverter conforms with the EMC Directive and affix the CE marking on the inverter.

- EMC Directive: 2004/108/EC
- Standard(s): EN61800-3:2004 (Second environment / PDS Category "C3")

Note: First environment
Environment including residential buildings. Includes buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.
Second environment
Environment including all buildings except buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.

- Note

Set the EMC filter valid and install the inverter and perform wiring according to the following instructions.

* The inverter is equipped with a built-in EMC filter. Set the EMC filter valid. (The EMC filter is invalid when shipped from the factory. (The FR-F720-00046 and 00077 are always valid.))
* Connect the inverter to an earthed power supply.
* Install a motor and a control cable according to the instructions written in the EMC Installation Guidelines (BCN-A21041-204).
* The cable length between the inverter and the motor is 5 m ( 16.4 feet) maximum.
* Confirm that the final integrated system with the inverter conforms with the EMC Directive.


## (2) Low Voltage Directive

We have self-confirmed our inverters as products compliant to the Low Voltage Directive (Conforming standard EN 50178) and affix the CE mark on the inverters.

## Outline of instructions

* Do not use an earth leakage current breaker as an electric shock protector without connecting the equipment to the earth. Connect the equipment to the earth securely.
* Wire the earth terminal independently. (Do not connect two or more cables to one terminal.)
* Use the cable sizes on page 8 under the following conditions.
- Surrounding air temperature: $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ maximum

If conditions are different from above, select appropriate wire according to EN60204 Appendix C TABLE 5.

* Use a tinned (plating should not include zinc) crimping terminal to connect the ground cable. When tightening the screw, be careful not to damage the threads.
For use as a product compliant with the Low Voltage Directive, use PVC cable whose size is indicated on page 8.
* Use the moulded case circuit breaker and magnetic contactor which conform to the EN or IEC Standard.
* When using an earth leakage current breaker, use a residual current operated protective device (RCD) of type B (breaker which can detect both AC and DC). If not, provide double or reinforced insulation between the inverter and other equipment, or put a transformer between the main power supply and inverter.
* Use the inverter under the conditions of overvoltage category II (usable regardless of the ground condition of the power supply), overvoltage category III (usable with the earthed-neutral system power supply, 400V class only) and pollution degree 2 or lower specified in IEC664.
- To use the inverter of 00770 or more (IP00) under the conditions of pollution degree 2 , install it in the enclosure of IP $2 X$ or higher.
- To use the inverter under the conditions of pollution degree 3, install it in the enclosure of IP54 or higher.
- To use the inverter of 00620 or less (IP20) outside of an enclosure in the environment of pollution degree 2 , fix a fan cover with fan cover fixing screws enclosed.

* On the input and output of the inverter, use cables of the type and size set forth in EN60204 Appendix C.
* The operating capacity of the relay outputs (terminal symbols A1, B1, C1, A2, B2, C2) should be 30VDC, 0.3A. (Relay output has basic isolation from the inverter internal circuit.)
* Control circuit terminals on page 4 are safely isolated from the main circuit.
* Environment

|  | During Operation | In Storage | During Transportation |
| :--- | :---: | :---: | :---: |
| Surrounding air <br> temperature | $\mathrm{LD}:-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ to $\left.122^{\circ} \mathrm{F}\right)$ <br> SLD (initial setting): $-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right.$ <br> to $\left.104^{\circ} \mathrm{F}\right)$ | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ <br> $\left(-4^{\circ} \mathrm{F}\right.$ to $\left.+149^{\circ} \mathrm{F}\right)$ | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ <br> $\left(-4^{\circ} \mathrm{F}\right.$ to $\left.+149^{\circ} \mathrm{F}\right)$ |
| Ambient humidity | $90 \% \mathrm{RH}$ or less | $90 \% \mathrm{RH}$ or less | $90 \% \mathrm{RH}$ or less |
| Maximum altitude | $1000 \mathrm{~m}(3280.80$ feet $)$ | $1000 \mathrm{~m}(3280.80$ feet $)$ | $10000 \mathrm{~m}(32808 \mathrm{feet)}$ |

Details are given in the technical information "Low Voltage Directive Conformance Guide" (BCN-A21041-203). Please contact your sales representative.

## Appendix 2 Instructions for UL and cUL Compliance

（Conforming standard UL 508C，CSA C22．2 No．14）

## （1）Installation

This inverter is a UL／cUL Listed open type device for use inside an enclosure，or enclosed Type 1 device with a suitably rated enclosure．
For open type，design an enclosure so that the inverter surrounding air temperature，humidity and atmosphere satisfy the specifications．（Refer to page 1．）
The following UL／cUL Listed FR－F700 Series Inverters employ a UL Type 1 Enclosure－Suitable for Installation in a Compartment Handling Conditioned Air（Plenum）：

Models FR－F720－00046，－00077，－00105，－00167，－00250，－00340，－00490，00630，－00770，－00930，followed by－NA suffix．
Models FR－F740－00023，－00038，－00052，－00083，－00126，－00170，－00250，－00310，－00380，－00470，－00620，followed by－NA suffix．

## Wiring protection

For installation in the United States，branch circuit protection must be provided in accordance with the National Electrical Code and any applicable provincial codes．
For installation in Canada，branch circuit protection must be provided in accordance with the Canadian Electrical Code and any applicable provincial codes．
Provide the appropriate UL and cUL listed Class RK5，Class T or Class L type fuse or UL489 molded case circuit breaker（MCCB）that is suitable for branch circuit protection in accordance with the table below．
Note，the Class L fuses can be used if the applicable current rating is larger than 600A．

| FR－F720－पロロロロ－NA | 00046 | 00077 | 00105 | 00167 | 00250 | 00340 | 00490 | 00630 | 00770 | 00930 | 01250 | 01540 | 01870 | 02330 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |


| Rated fuse voltage（V） |  | 240 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Fuse maximum allowable rating（A）＊ | Without power factor improving reactor | 15 | 20 | 30 | 40 | 60 | 80 | 150 | 175 | 200 | 225 | 300 | 350 | 400 | 500 |
|  | With power factor improving reactor | 15 | 20 | 20 | 30 | 50 | 70 | 125 | 150 | 200 | 200 | 250 | 300 | 350 | 400 |
| Molded case circuit breaker （MCCB） <br> maximum allowable rating $(A)^{*}$ |  | 15 | 15 | 25 | 40 | 60 | 80 | 110 | 150 | 175 | 225 | 300 | 350 | 450 | 500 |
| FR－F720－पロロロロ－NA |  | 03160 | 03800 | 04750 |  |  |  |  |  |  |  |  |  |  |  |
| Rated fuse voltage（V） |  | 240 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Fuse maximum allowable rating（A）＊ | Without power factor improving reactor | － | － | － |  |  |  |  |  |  |  |  |  |  |  |
|  | With power factor improving reactor | 500 | 600 | 700 |  |  |  |  |  |  |  |  |  |  |  |
| Molded case circuit breaker （MCCB） maximum allowable rating（A）＊ |  | 700 | 900 | 1000 |  |  |  |  |  |  |  |  |  |  |  |


| FR－F740－ㅁㅁㅁㅁㅁNA |  | 00023 | 00038 | 00052 | 00083 | 00126 | 00170 | 00250 | 00310 | 00380 | 00470 | 00620 | 00770 | 00930 | 01160 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated fuse voltage（V） |  | 480 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Fuse maximum allowable rating（A）＊ | Without power factor improving reactor | 6 | 10 | 15 | 20 | 30 | 40 | 70 | 80 | 90 | 110 | 150 | 175 | 200 | 250 |
|  | With power factor improving reactor | 6 | 10 | 10 | 15 | 25 | 35 | 60 | 70 | 90 | 100 | 125 | 150 | 175 | 200 |
| Molded case circuit breaker （MCCB） <br> maximum allowable rating（A）＊ |  | 15 | 15 | 15 | 20 | 30 | 40 | 60 | 70 | 90 | 100 | 150 | 175 | 225 | 250 |


| FR－F740－ㅁㅁㅁㅁ－NA |  | 01800 | 02160 | 02600 | 03250 | 03610 | 04320 | 04810 | 05470 | 06100 | 06830 | 07700 | 08660 | 09620 | 10940 | 12120 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated fuse voltage（V） |  | 500 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Fuse maximum allowable rating（A）＊ | Without power factor improving reactor | － | － | － | － | － | － | － | － | － | － | － | － | － | － | － |
|  | With power factor improving reactor | 300 | 350 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1350 | 1500 | 1800 | 2000 |
| Molded case circuit breaker （MCCB） maximum allowable rating（A）＊ |  | 450 | 500 | 600 | 800 | 900 | 1000 | 1200 | 1200 | 1200 | 1600 | 1600 | 2000 | 2000 | 2500 | 3000 |

[^2]
## (2) Wiring of the power supply and motor

For wiring the input (R/L1, S/L2, T/L3) and output ( $\mathrm{U}, \mathrm{V}, \mathrm{W}$ ) terminals of the inverter, use the UL Listed copper, stranded wires (rated at $75^{\circ} \mathrm{C}\left(167^{\circ} \mathrm{F}\right)$ ) and round crimping terminals. Crimp the crimping terminals with the crimping tool recommended by the terminal maker.

## (3) Short circuit ratings

- 200 V class

Suitable For Use in A Circuit Capable Of Delivering Not More Than 100kA rms Symmetrical Amperes, 264V Maximum.

- 400 V class

Model 01160 or less
Suitable For Use in A Circuit Capable Of Delivering Not More Than 100kA rms Symmetrical Amperes, 528V Maximum. Model 01800 or more
Suitable For Use in A Circuit Capable Of Delivering Not More Than 100kA rms Symmetrical Amperes, 550V Maximum.

## (4) Motor overload protection

This inverter is certified as a motor overload protection device by UL.
When using the electronic thermal relay function as motor overload protection, set the rated motor current to Pr. 9 Electronic thermal O/L relay.

Electronic thermal relay function operation characteristic


This function detects the overload (overheat) of the motor, stops the operation of the inverter's output transistor, and stops the output. (The operation characteristic is shown on the left)

- When using the Mitsubishi constant-torque motor

1) Set "1" in Pr. 71 . (This provides a $100 \%$ continuous torque characteristic in the low-speed range.)
2) Set the rated current of the motor in Pr. 9.
*1 When 50\% of the inverter rated output current (current value) is set in Pr. 9
*2 The \% value denotes the percentage to the inverter rated output current. It is not the percentage to the motor rated current.
*3 When you set the electronic thermal relay function dedicated to the Mitsubishi constant-torque motor, this characteristic curve applies to operation at 6 Hz or higher.

## CAUTION

- Protective function by electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-off.
- When multiple motors are operated by a single inverter, protection cannot be provided by the electronic thermal relay function. Install an external thermal relay to each motor.
- When the difference between the inverter and motor capacities is large and the setting is small, the protective characteristics of the electronic thermal relay function will be deteriorated. In this case, use an external thermal relay.
A special motor cannot be protected by the electronic thermal relay function. Use the external thermal relay.
Electronic thermal relay may not function when $5 \%$ or less of inverter rated current is set to electronic thermal relay setting.

MEMO

## MEMO

MEMO
*The manual number is given on the bottom left of the back cover.

| Print Date | *Manual Number | Revision |
| :---: | :---: | :---: |
| Sep. 2004 | IB(NA)-0600218ENG-A | First edition |
| Dec. 2004 | IB(NA)-0600218ENG-B | Additions - FR-F720-03160 to $04750-$ NA - FR-F740-04320 to $12120-$ NA |
| May 2006 | IB(NA)-0600218ENG-C | Additions <br> - Electronic thermal relay function operation characteristic. <br> - Pr. 539 Modbus-RTU communication check time interval <br> - Voltage/current input switch |
| Nov. 2007 | IB(NA)-0600218ENG-D | Additions <br> - Breaker selection when using the inverter as UL or cUL listed product <br> - Pr. 495 Remote output selection setting value "10, 11" |
| Sep. 2009 | IB(NA)-0600218ENG-E | Additions <br> Pr. 59 Remote function selection setting value "11", "12", "13" <br> Pr. 29 Acceleration/deceleration pattern selection setting value "6" <br> Pr. 30 Regenerative function selection setting value "10", "11", "20", "21" <br> Pr. 128 PID action selection setting value "110", "111", "120", "121" <br> Pr. 167 Output current detection operation selection setting value "10", "11" <br> Pr. 178 to Pr. 189 Input terminal function selection setting value "70", "71", "72" <br> Pr. 190 to Pr. 196 Output terminal function selection setting value "48", "79", "85", <br> "148", "179", "185" <br> Pr. 261 Power failure stop selection setting value "21", "22" <br> Pr. 522 Output stop frequency <br> Pr. 653 Speed smoothing control, Pr. 654 Speed smoothing cutoff frequency <br> Pr. 553 PID deviation limit, Pr. 554 PID signal operation selection, C42 (Pr.934) PID <br> display bias coefficient, C43 (Pr.934) PID display bias analog value, C44 (Pr.935) PID <br> display gain coefficient, C45 (Pr.935) PID display gain analog value <br> Pr. 799 Pulse increment setting for output power <br> Partial modification <br> Pr. 153 Zero current detection time setting range " 0 to 10s" <br> Appendix 1 Instructions for compliance with the EU Directives |
| May 2010 | IB(NA)-0600218ENG-F | Additions <br> Two plug-in options available Pr. 147, Pr. 296, Pr. 297, Pr. 414, Pr. 415, Pr. 498, Pr. 502, Pr. 505 to Pr. 515, Pr. 665, Pr. 753 to Pr. 769, Pr. 774 to Pr. 779, Pr. 826 to Pr. 865, Pr. 870, Pr. 997, Pr. 999, Pr. CH, AUTO Pr. 128 PID action selection setting value " 70 to 101" <br> Pr. 30 Regenerative function selection setting value "100, 101, 120, 121" <br> Pr. 54 CA terminal function selection and Pr. 158 AM terminal function selection setting value "70" <br> Pr. 178 to Pr. 189 (input terminal function selection) setting value "50, 51, 77, 78" Pr. 190 to Pr. 196 (output terminal function selection) setting value "49 to 54, 67, 149 to 154, 167" <br> Pr. 573 4mA input check selection setting value "2, 3, 4" <br> Error message <br> LOCd Password locked <br> E.OP2 Communication option fault <br> E. 2 Option fault <br> E.PCH Pre-charge fault <br> E.LCl 4mA input fault <br> Partial modification <br> Pr. 263 Subtraction starting frequency setting range " 0 to $120 \mathrm{~Hz}, 9999$ " to " 0 to 400Hz, 9999" <br> Pr. 885 Regeneration avoidance compensation frequency limit value setting range " 0 to $10 \mathrm{~Hz}, 9999$ " to " 0 to $30 \mathrm{~Hz}, 9999$ " |

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- Mitsubishi inverters are not designed or manufactured to be used in equipment or systems in situations that can affect or endanger human life.
- When considering this product for operation in special applications such as machinery or systems used in passenger transportation, medical, aerospace, atomic power, electric power, or submarine repeating applications, please contact your nearest Mitsubishi sales representative.
- Although this product was manufactured under conditions of strict quality control, you are strongly advised to install safety devices to prevent serious accidents when it is used in facilities where breakdowns of the product are likely to cause a serious accident.
- Please do not use this product for loads other than three-phase induction motors.

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When playing this CD-ROM on Windows OS

- Operating environment
- The following system is required to read instruction manuals contained in this CD-ROM.

| Item | Specifications |
| :---: | :--- |
| OS | Microsoft Windows 95 OSR 2.0, Windows 98 Second Edition, Windows Millennium Edition, <br> Windows NT 4.0 with Service Pack 6, Windows 2000 with Service Pack 2, <br> Windows XP Professional or Home Edition, Windows XP Tablet PC Edition |
| CPU | Intel Pentium processor |
| Memory | 64MB of RAM |
| Hard disk | 24MB of available hard-disk space |
| CD-ROM drive | Double speed or more (more than quadruple speed is recommended) |
| Monitor | 800x600 dot or more |
| Application | Acrobat Reader 4.05 or more |

- Operating method of this CD-ROM

How to read instruction manuals
Step 1. Start Windows and place this CD-ROM in the CD-ROM drive.
Step 2. "700 series documentation" PDF automatically opens.
Step 3. Click a PDF file name of the manual you want to read in the "INSTRUCTION MANUAL" list.
Step 4. PDF manual you clicked opens.

* Manual opening of this CD-ROM

Step 1. Start Windows and place this CD-ROM in the CD-ROM drive.
Step 2. Select a CD-ROM drive (example: D drive) of "My computer" and click the right mouse button. Then, click "open" in the context menu.
Step 3. Open "INDEX.PDF" in the opened folder.
Step 4. "700 series documentation" PDF opens. Operates according to the steps from "Step 3" of "How to read instruction manuals"

- PDF data of the instruction manual are stored in "MANUAL" folder on this CD-ROM.


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[^0]:    Thank you for choosing this Mitsubishi Inverter．
    Please read through this Installation Guideline and a CD－ROM enclosed to operate this inverter correctly． Do not use this product until you have a full knowledge of the equipment，safety information and instructions．
    Please forward this Installation Guideline and the CD－ROM to the end user．

[^1]:    ＊If an error occurs when using the FR－PU04，＂Fault 14＂is displayed on the FR－PU04

[^2]:    ＊Maximum allowable rating by US National Electrical Code at SLD rating． Exact size must be chosen for each installation．

